

G. C. E. (Advanced Level)

Combined Mathematics

Teacher's Instruction Manual

Grade 12



Department of Mathematics
Faculty of Science and Technology
National Institute of Education

Combined Maths

Grade 12

Teacher's Instruction Manual

(Implementation in 2009)



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Director General's Message

Curriculum developers of the NIE were able to introduce Competency Based Learning and Teaching curricula for grades 6 and 10 in 2007 and were also able to extend it to 7, 8 and 11 progressively every year and even to GCE (A/L) classes in 2009. In the same manner syllabi and Teacher's Instructional Manuals for grades 12 and 13 for different subjects with competencies and competency levels that should be developed in students are presented descriptively. Information given on each subject will immensely help the teachers to prepare for the Learning – Teaching situations.

I would like to mention that curriculum developers have followed a different approach when preparing Teacher's Instructional Manuals for Advanced Level subjects when compared to the approaches they followed in preparing Junior Secondary and Senior Secondary curricula. (Grades 10, 11)

In grades 6, 7, 8, 9, 10 and 11 teachers were oriented to a given format as to how they should handle the subject matter in the Learning – Teaching process, but in designing AL syllabi and Teacher's Instructional Manuals freedom is given to the teachers to work as they wish.

At this level we expect teachers to use a suitable learning method from the suggested learning methods given in the Teacher's Instructional Manuals to develop competencies and competency levels relevant to each lesson or lesson unit.

Whatever the learning approach the teacher uses it should be done effectively and satisfactorily to realize the expected competencies and competency levels.

I would like to note that the decision to give this freedom is taken, considering the importance of GCE (A/L) examinations and the sensitivity of other stakeholders who are in the education system to the Advanced Level examination. I hope that this Teacher's Instructional Manual would be of great help to teachers.

I hope the information, methods and instructions given in this Teacher's Instructional Manual will provide proper guidance to teachers to awaken the minds of our students.

Professor Lal Perera

Director General

National Institute of Education

Forward

Action taken over long years of the past to retain the known and learn the predetermined has made us little able today to construct even what is. The first curriculum reform of the new millennium on secondary education that comes to being with a drastic change in the learning-teaching process at school level attempts to overcome this inability while bringing about a set of worthy citizens for the country who are capable of revising the known, exploring the undetermined and constructing what might be.

If you are a teacher teaching this subject or any other subject in grades 6 to 11, it will not be difficult for you to align yourself with the new learning-teaching approaches that are recommended in a considerable way for the GCE (A/L) as well. This reform calls the teacher to identify competency levels under each competency and plan activities to achieve them. The teachers entering the new role of transformation should understand that the procedures which emphasize the teacher in the learning-teaching process are of limited use for the present and that it is more meaningful for the children to learn co-operatively sharing their experiences. This situation, however, requires the teachers to provide a new direction for their teaching by selecting new learning-teaching methods that emphasize the student over the teacher.

If you study the Teachers' Instructional Guides (TIGs) prepared by the National Institute of Education for Mathematics, Science, Health & Physical Education, Technology and Commerce subject of grades 6 to 11, you certainly will be able to acquire a good understanding on the student-centred, competency based and activity- oriented approaches we have recommended for learning and teaching. The activities presented in these Guides attempt to bring learning, teaching assessment and evaluation on to the same platform and to help you to adopt co-operative learning techniques on the basis of the 5E Model.

Considering the need to establish an innovative teaching force we have selected just a few activities from the relevant activity continuum incorporated in the TIGs. Yet we have given you a vast freedom to plan your own activities to suit the subject and the class requirements by studying the exemplar activities in the Guides and improving your understanding on the principles underlying the reform. The activities incorporated in the TIG, provide you with four types of information. At the beginning of each activity you come across the final outcome that the children are expected to achieve through each activity. This learning outcome named as 'Competency' is broad and long-term. The competency level stated next highlight one out of the number of abilities that the children have to develop to realize the competency.

The above explanation shows us that the competency levels are more specific and of a shorter duration when compared to the competency. The next section of the Guide presents a list of behaviours that the teacher has to observe at the end of each activity. To facilitate the task of both the teacher and the students, an attempt has been made to limit the number of such behaviours to five. These behaviours referred to as learning outcomes are more specific than the competency level. They include three abilities derived from the subject and two others derived from the learning teaching process. Out of the three subject abilities listed in an order of difficulty, the teacher has to direct the children to realize at least the first two through the exploration. The next section of the activity presents what the teacher should do to engage the children for the exploration. Although the implementation of each and every activity starts with this step of engagement, the teachers should not forget that activity planning should begin with the exploration which is the second 'E' of the 5E Model.

Instructions for the group exploration from the next section of the exemplar activities the teacher plans these instructions in such a way to allow different groups studying different facets of the same problem to reach the expected ends through a variety of learning-teaching methods. For this, further the teacher can select either Inquiry-based Learning carried out through a series of questions or Experiential Learning where children learn by doing. It is the responsibility of the GCE (A/L) teacher to use the knowledge that the children acquire by any of the above methods to solve problems that are specific to the subject or that runs across a number of subjects of the curriculum is meaningful to plan such problem-based learning-teaching methods on the basis of real-life situations. For this you can select dilemmas, hypothetical situations, analogies or primary sources. Some techniques that can be used for the explorations are reading, information management, reflection, observation, discussion, formulation and testing of hypotheses, testing predictions, preparing questions and answers, simulation, problem solving and aesthetic activities such as drawing or composing. There is room here even for memorization although it is considered as a form of mechanical learning.

The students explore in small groups. Instead of depending on the knowledge available to the teacher, they attempt to construct their own knowledge and meaning with the support of the teacher. Moreover, they interact with others in the group to learn from others and also to improve the quality of their exploration findings. All this works successfully only if the teacher is capable of providing the students with the reading material and the other inputs they are in need of. The teacher also has to support student learning throughout the learning process by moving from one group to another. Although it is the discovery that is prominent in this type of learning you have to recognize this as a guided discovery rather than a free discovery. There is no doubt that students learning likewise with instructional scaffolding both by the teacher and the peers acquire a whole lot of worthwhile experiences that they find useful later in life.

Explanation follows the second stage of exploration. The small groups get ready to make innovative, team presentations on their findings. The special feature here is that the children have selected novel methods for their presentations. The responsibility for the presentation is also shared by all members of the group. In the next step of elaboration the children get the opportunity to clarify the unclear, correct the incorrect and fill any gaps that are left. They also can go beyond the known to present new ideas. All activities end with a brief lecture made by the teacher. This stage allows the teacher to go back to the transmission role. The teacher also has to deliver this lecture covering all the important points that the syllabus has prescribed for the relevant competency level. Step 3 of each Activity Plan guides the teachers in this compulsory final elaboration.

To overcome many problems that are associated with the general system of education today, the National Institute of Education has taken steps to move the teachers to the new transformation role recommended for them. This role that starts with a transaction gets extended to a lengthy exploration, a series of student explorations and elaborations and a summative transmission by the teacher. The students involve themselves in the exploration using reading material and other quality inputs provided to them by the teacher.

The students attend school daily to learn joyfully. They achieve a number of competencies that they need to be successful in life and the world of work. They prepare themselves for nation building by developing thinking skills, social skills and personal skills. For the success of all this, an examination system that inquires into the ability of students to face real challenges of life is very much needed in place of an examination system that focuses on the knowledge acquired by children through memorizing answers to model questions.

A number of activities have already begun at the national level to protect the real nature of school-based assessments. The written tests have been minimised to gain recognition for school-based assessments. Compulsory question has been incorporated in the term tests along with a scheme of authentic evaluation to ensure real outcomes of learning. It is the co-ordinated responsibility of all citizens of the country to open up doors for a new Sri Lanka by thriving for the success of this new programme on the basis of sound instructional leadership and quality assurance by the management.

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Combined Maths I

Com. Level	Learning Outcomes	Guidelines for Subject Matter	No. of Periods
1.1	1. Explains the evolution of the number system. 2. Represents a real number geometrically.	<p>Explain briefly the evolution from the inception of the use of numbers upto the real number system.</p> <p>Remind the knowledge of pupils about the sets of natural numbers, integers, rational numbers, irrational numbers and real numbers.</p> <p>Show that all sets above are Sub sets of \mathbb{R} and direct the pupils to denote it in a Venn Diagram.</p> <p>Introduce the symbols</p> <p>Remind the representation of a real number on a number line.</p>	02
1.2	1. Classifies decimal numbers 2. Classifies real numbers 3. Rationalises the denominator of expressions with surds.	<div style="text-align: center;"> <p>Decimal Numbers</p> <pre> graph TD A[Decimal Numbers] --- B[Finite (finite decimals)] A --- C[Infinite (infinite decimals)] C --- D[Recurring decimals] C --- E[Non-recurring decimals] </pre> </div> <div style="text-align: center; margin-top: 20px;"> <p>Real Numbers</p> <pre> graph TD A[Real Numbers] --- B[Rational numbers] A --- C[Irrational numbers] </pre> </div> <p>Introduce surds and explain the rationalisation of their denominators.</p>	02

Com. Level	Learning Outcomes	Guidelines for Subject Matter	No. of Periods
26.2	<p>5. Deduces the length of a line segment joining two points with given coordinates.</p> <p>Deduces the coordinates of the point that divides a line segment joining two given points internally or externally in a given ratio.</p>	<p>Deduce that if $A \equiv (x_1, y_1)$ and $B \equiv (x_2, y_2)$ then</p> $ AB = \sqrt{(x_1 - x_2)^2 + (y_1 - y_2)^2}.$ <p>AB is always positive.</p> <p>The coordinates of a point dividing the line segment AB where $A \equiv (x_1, y_1)$ and $B \equiv (x_2, y_2)$ in the ratio $m:n$.</p> <p>(i) internally is given by</p> $P \equiv \left(\frac{nx_1 + mx_2}{m+n}, \frac{ny_1 + my_2}{m+n} \right)$ <p>(ii) externally is given by</p> $P \equiv \left(\frac{nx_1 - mx_2}{m-n}, \frac{ny_1 - my_2}{m-n} \right),$	03
26.3	Finds the area of a triangle when the coordinates of the vertices are given.	<p>The area of the triangle ABC when $A \equiv (x_1, y_1)$, $B \equiv (x_2, y_2)$ and $C \equiv (x_3, y_3)$. Show that the area of a plane figure enclosed by straight lines can be determined by separating it into triangles.</p> $\Delta = \frac{1}{2} x_1(y_2 - y_3) + x_2(y_3 - y_1) + x_3(y_1 - y_2) $	01
16.1	<p>1. Explains trigonometric ratios.</p> <p>2. Introduces trigonometric ratios as circular functions.</p> <p>3. Introduces the domain and the range of circular functions.</p>	<p>Define trigonometric ratios using the cartesian coordinate system.</p> <p>Show that trigonometric ratio of a variable angle is a function of that angle. Introduce these ratios as circular functions.</p> <p>Introduce the domain and the range of circular functions.</p>	03

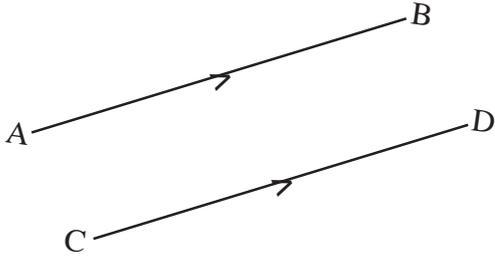
Com. Level	Learning Outcomes	Guidelines for Subject Matter	No. of Periods				
16.3	<p>3. Describes the periodic property of circular functions</p>	<table border="1" style="margin-left: auto; margin-right: auto;"> <tr> <td style="padding: 5px;">(2) sine(+)</td> <td style="padding: 5px;">(1) all(+)</td> </tr> <tr> <td style="padding: 5px;">(3) tangent(+)</td> <td style="padding: 5px;">(4) cosine(+)</td> </tr> </table> <p>When an angle is increased by an integral multiple of 2π, the radius vector reaches the initial position after a single or more revolutions. Therefore $\sin(\theta + 2n\pi)$ and $\cos(\theta + 2n\pi)$ have the same trigonometric ratios.</p>	(2) sine(+)	(1) all(+)	(3) tangent(+)	(4) cosine(+)	05
	(2) sine(+)	(1) all(+)					
	(3) tangent(+)	(4) cosine(+)					
<p>4. Obtains the trigonometric ratios of $\frac{\pi}{2} \pm \theta$, $\pi \pm \theta$, $(-\theta)$... in terms of the trigonometric ratios of θ.</p>	<p>Obtain the trigonometric ratios of $\frac{\pi}{2} \pm \theta$, $\pi \pm \theta$, $(-\theta)$... in terms of the trigonometric ratios of θ using geometrical methods.</p>						
<p>5. Writes trigonometric ratios of angles of given magnitude.</p>	<p>Direct students to find out the values of \sin, \cos and \tan of the angles $30^\circ, 45^\circ, 60^\circ, \dots$</p>						
	<p>1. Represents the circular functions graphically.</p>	<p>Introduce the graphs of \sin, \cos, \tan, \cot, \sec and cosec.</p>					
	<p>2. Draws graphs of combined circular functions.</p>	<p>Direct students to draw the graphs of $\sin^2 \theta$, $\cos^2 \theta$, $\sin \theta \cos \theta$, $\sin^2 \theta + \cos^2 \theta$, etc.</p>					
	<p>3. Obtains the general solutions of trigonometric functions.</p>	<p>Obtain the general solutions of;</p> <p>(i) $\sin \theta = \sin \alpha$ as $\theta = n\pi + (-1)^n \alpha$</p> <p>(ii) $\cos \theta = \cos \alpha$ as $\theta = n\pi \pm \alpha$</p> <p>(iii) $\tan \theta = \tan \alpha$ as $\theta = n\pi + \alpha$</p> <p>Where n is any integer and α is value which satisfies the above equations.</p>					

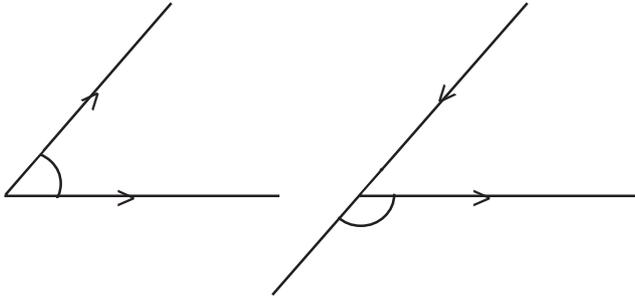
Com. Level	Learning Outcomes	Guidelines for Subject Matter	No. of Periods
4.1	1. Defines a polynomial in a single variable. 2. Distinguishes among Linear, Quadratic and Cubic functions.	Defining a polynomial introduce the terms degree, principal term and principal coefficient of a polynomial. Introduce the general form of a linear function as $y = ax + b$ where $a \neq 0$, quadratic function as $y = ax^2 + bx + c$; Cubic function as $y = ax^3 + bx^2 + cx + d$,	01
4.2	3. States the properties of identical polynomials. 1. Explains the basic Mathematical operations on polynomials.	Show that if $P(x) = Q(x)$ then for all a , $P(a) = Q(a)$ and coefficient of corresponding terms are equal. Revise the prior knowledge relating to addition, subtraction and multiplication.	02
4.3	2. Divides a polynomial by another polynomial. 1. States the algorithm for division. 2. States the remainder theorem. 3. Proves the remainder theorem. 4. States the Factor theorem	Introduce the notation $\frac{P(x)}{Q(x)}$ for $P(x)$ divided by $Q(x)$. Using examples explain the synthetic division and long division. Explain $\text{Dividend} = \text{Quotient} \times \text{Divisor} + \text{Remainder}$ Express that when a polynomial $P(x)$ is divided by $Q(x)$ the remainder is $R(x)$. Prove the remainder theorem. Express that if $P(x)$ is a factor of $Q(x)$	05

Com. Level	Learning Outcomes	Guidelines for Subject Matter	No. of Periods
17.3	Constructs multiplication formulae	(iv) (v) $\tan(A + B) = \frac{\tan A + \tan B}{1 - \tan A \cdot \tan B}$ (vi) $\tan(A - B) = \frac{\tan A - \tan B}{1 + \tan A \cdot \tan B}$ $\sin C + \sin D = 2 \sin\left(\frac{C+D}{2}\right) \cos\left(\frac{C-D}{2}\right)$	03
17.4	1. Derives trigonometric formula for double, triple and half angles.	$= 2 \cos^2 A - 1$ $\tan 2A = \frac{2 \tan A}{1 - \tan^2 A}$ $\sin 3A = 3 \sin A - 4 \sin^3 A$ $\cos 3A = 4 \cos^3 A - 3 \cos A$ <p>Obtain formulae $\sin \frac{A}{2}$, and using the above identities. Direct students to prove trigonometric identities related to angles of a triangle. Also show that an expression of the form can be transformed to the form using the above results.</p>	03

Com. Level	Learning Outcomes	Guidelines for Subject Matter	No. of Periods
22.3	1. Expresses $\lim_{x \rightarrow a} \frac{x^n - a^n}{x - a} = na^{n-1}$ where “ n ” is any rational number. 2. Solves problems using above results involving limits.	6. , 7. , $n \in \mathbb{N}$ When 8. When f is a polynomial function for all . 9. If $f(x) = g(x)$ for all values of x except at $x = a$ in an interval including a , then . The proofs of the above theorems are not expected. Explain their use in solving problems with examples. Prove the theorem for positive integral values of n , and deduce it for negative integral values of n . State that the theorem is true for any rational number n . Direct students to solve suitable problems.	03
22.4	1. States the sandwich theorem. (squeezes lemma) 2. States that $\lim_{x \rightarrow 0} \frac{\sin x}{x} = 1$ 3. Proves the above result.	In an open interval containing a if for all values of x including or excluding a $f(x) \leq h(x) \leq g(x)$ and $\lim_{x \rightarrow a} f(x) = l = \lim_{x \rightarrow a} g(x) \text{ then } \lim_{x \rightarrow a} h(x) = l.$ The proof of this theorem is not necessary. State that (x is measured in radians) When x is measured in radians proves that by a geometrical method. Using the above results deduce that	03

Combined Maths II

Com. Level	Learning Outcomes	Guidelines for Subject Matter	No. of Periods
1.1	<ol style="list-style-type: none"> 1. Explains the difference between scalar quantities and scalars. 2. Defines a vector quantity. 3. Represents a vector geometrically. 4. Defines a “geometrical vector” 5. Expresses the algebraic notation of a vector quantity. 6. Classifies vectors. 7. Defines the modulus of a vector. 8. States the conditions necessary for two vectors to be equal. 	<p>Explain that a quantity having only a magnitude and expressed using a certain measuring unit is called a scalar quantity and that numerical value without unit is a scalar.</p> <p>Explain vector quantities as those with magnitude, direction and obeying triangle law of addition. [Triangle law of addition will be given later].</p> <p>Present that the vector represented by the line segment AB from A to B is denoted by \vec{AB}.</p>  <p>Explain that a line segment with a magnitude and a direction is geometrically a vector. A vector does not have dimensions although a vector quantity has dimensions.</p> <p>Show that the vector “ ” is denoted by the symbol \vec{a} or \mathbf{a} (In print, letters in bold print are used to denote vectors). State also that different letters are used to denote different vectors.</p> <p>Show how vectors can be classified into free vectors, sliding vectors and tied vectors.</p> <p>Introducing the magnitude of a vector as its modulus, show that the modulus of \vec{a} is denoted by \vec{a}. Explain that \vec{a} is always a positive scalar, because it is the length of a line segment.</p> <p>Vectors with equal magnitude and in the same direction are called equal vectors.</p> 	03

Com. Level	Learning Outcomes	Guidelines for Subject Matter	No. of Periods
	15. Multiplies a vector by a scalar.	<p>When \vec{a} is a vector and k is a scalar, introduce that as k times \vec{a}. Discuss the cases when $k > 0$ and $k < 0$. Give examples. Describe the vector $k\vec{a}$.</p> 	
	16. Identifies the angle between two vectors.	Introduce the angle between two vectors as the angle, θ , between their directions.	
	17. Identifies parallel vectors.	State that vectors whose lines of action are parallel are called “parallel vectors”.	
	18. State the conditions necessary for two vectors to be parallel.	<p>Show that \vec{a} and \vec{b} are parallel, if $\vec{a} = k\vec{b}$ where k is a non zero scalar.</p> <p>If \vec{a} and \vec{b} are two non zero vectors and λ and μ are scalars the sufficient and necessary conditions for $\lambda\vec{a} = \mu\vec{b}$ is $\frac{\lambda}{\mu} = \frac{a}{b}$.</p>	
	19. Defines a “unit vector”.	<p>Define a vector of unit magnitude as a unit vector. Show that if \vec{a} is a given vector in the direction of \vec{a}.</p> $\text{then } \underline{u} = \frac{\vec{a}}{ \vec{a} }$	
	20. Resolves a vector in any two given directions.	<p>Show how a given vector can be resolved in two given directions by constructing a parallelogram with given vector as a diagonal and adjacent sides in the required directions.</p> <p>Show how a given vector can be resolved in two given mutually perpendicular directions by constructing a rectangle with the given vector as a diagonal.</p>	

Com. Level	Learning Outcomes	Guidelines for Subject Matter	No. of Periods
	<p>2. States that the scalar product of two vectors is a scalar.</p> <p>3. States the properties of scalar product.</p> <p>4. Interprets scalar product geometrically.</p> <p>5. Solves simple geometric problems involving scalar product.</p>	<p>which a right handed screw descends when it is screwed from the line of action of \hat{a} towards the line of action of \hat{b}, is a unit vector in a direction perpendicular to both \hat{a} and \hat{b}. { $\hat{a}, \hat{b}, \hat{c}$ forms a right handed set } State that this is also known as the cross product of \hat{a} and \hat{b}. If \hat{a} or \hat{b} or \hat{c}, define \hat{c} as null vector.</p> <p>Explain that $\hat{a} \cdot \hat{a}$ is a scalar. Show that $\underline{a} \cdot \underline{b} = 0$ if \underline{a} and \underline{b} are perpendicular, where $\underline{a} = a\hat{a}$ and $\underline{b} = b\hat{b}$.</p> <p>(i) Commutative law (ii) Distributive law</p> <p>Show that, when \hat{c} is a unit vector, $\hat{c}\hat{c}$ is the orthogonal projector of \hat{c} on \hat{c}.</p> <p>Explain with examples.</p>	
2.1	<p>1. Describes the concept of a particle.</p> <p>2. Describes the concept of a force.</p> <p>3. States that a force is a localized vector.</p> <p>4. Represents a force geometrically.</p>	<p>State that a particle is considered as a solid body having very small dimensions compared with other distances related to its motion.</p> <p>Show that as a particle can be considered as a sphere of zero radius having a mass, it can be represented geometrically by a point.</p> <p>Introduce force as an action which creates a motion in a body at rest or which changes the nature of the motion in the case of a moving body.</p> <p>A force has a magnitude, direction and a line of action. Therefore it can be treated as a localized vector.</p> <p>State that Newton (N) is the unit by which the magnitude of a force is measured. Show that a force can be represented by a line segment whose length is proportional to the magnitude of the force and drawn in its direction.</p>	04

Com. Level	Learning Outcomes	Guidelines for Subject Matter	No. of Periods
2.2	10. Resolves a given force into two components in two given directions.	Show the method of resolving a given force in two directions by constructing a parallelogram with its adjacent sides in the two given directions and its diagonal representing the given force. Show that the effect of the two resolved parts is same as the effect of the given force.	06
	11. Resolves a given force into two components perpendicular to each other.	State that a force is resolved into two components perpendicular to each other for the convenience in solving problems and obtain the two components.	
	1. Determines graphically the resultant of three or more coplanar forces acting at a point. 2. Determines the resultant of three or more coplanar forces acting at a point by resolution.	Present the graphical method (polygon method) of determining the resultant of three or more coplanar forces acting at a point. Show that, if X and Y are the algebraic sums of the components of the forces when resolved in two given perpendicular directions then their resultant is also given by $\sqrt{X^2 + Y^2}$ and the angle α which the resultant makes with the direction of X is given by $\tan^{-1} \frac{Y}{X}$. Direct students to solve problems using these results. Condition to be fulfilled for the equilibrium of a coplanar system of forces acting on a particle.	
2.3	3. States the conditions necessary for a system of coplanar forces acting on a particle to be in equilibrium.	The algebraic sums of the resolved components in two given perpendicular directions are zero. i.e. $X=0, Y=0$.	06
	1. Explains what is meant by equilibrium. 2. States the conditions for equilibrium of a particle under the action of two forces.	Show that a particle acted upon by a system of coplanar forces is in equilibrium, if the resultant of the system of forces is zero. Show that if a particle under the action of two forces P and Q, is in equilibrium then P and Q are equal in magnitude and opposite in direction (i.e. they are collinear).	

Combined Maths

Grade 12

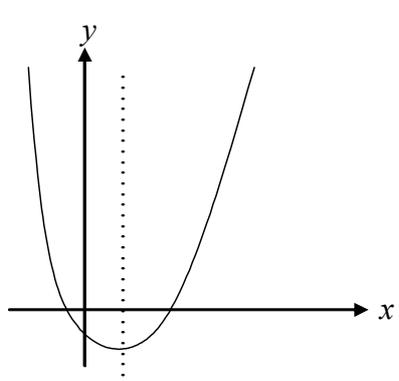
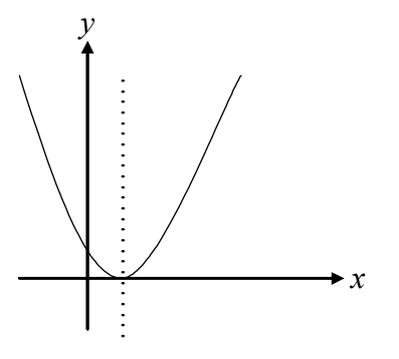
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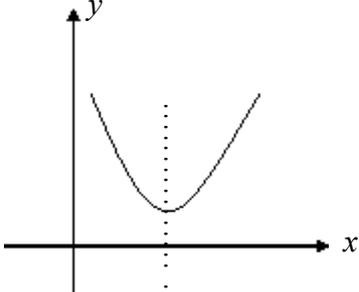
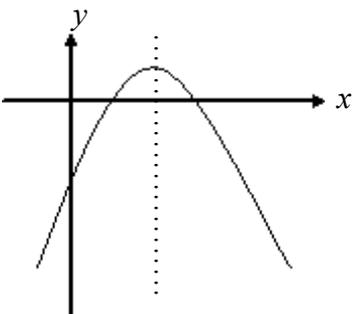
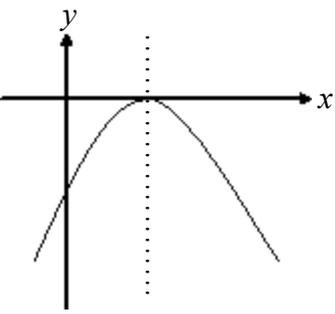
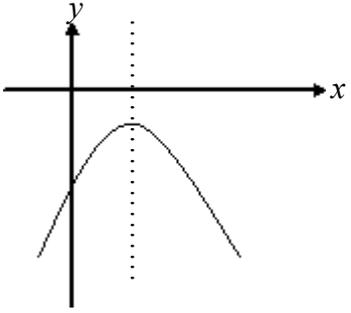
Second Term

Combined Maths I

Com. Level	Learning Outcomes	Guidelines for Subject Matter	No. of Periods																		
11.1	<p>1. Defines inequalities</p> <p>2. Represents inequalities on a real number line.</p> <p>3. Denotes inequalities in terms of interval notation.</p> <p>4. States the Trichotomy law.</p> <p>5. States and proves fundamental results on inequalities.</p>	<p>When “a” and “b” are real numbers</p> <p>(i) $a > b$ if and only if $(a-b)$ is positive and</p> <p>(ii) $a < b$ if and only if $(a-b)$ is negative</p> <p>Explain the concepts in these definitions using the number line</p> <p>Explain inequalities in terms of the number line.</p> <p>Introduce the following special sets which are intervals in \mathbb{R}.</p> <p>When $a, b \in \mathbb{R}$, $a < b$,</p> <table style="width: 100%; border-collapse: collapse;"> <thead> <tr> <th style="text-align: left;">Interval</th> <th style="text-align: left;">Notation</th> </tr> </thead> <tbody> <tr> <td>$\{x \in \mathbb{R} \mid a \leq x \leq b\}$</td> <td>$[a, b]$</td> </tr> <tr> <td>$\{x \in \mathbb{R} \mid a \leq x < b\}$</td> <td>$[a, b)$</td> </tr> <tr> <td>$\{x \in \mathbb{R} \mid a < x \leq b\}$</td> <td>$(a, b]$</td> </tr> <tr> <td>$\{x \in \mathbb{R} \mid a < x < b\}$</td> <td>$(a, b)$</td> </tr> </tbody> </table> <p>Explain following intervals as well.</p> <table style="width: 100%; border-collapse: collapse;"> <tbody> <tr> <td>$\{x \in \mathbb{R} \mid x \geq a\}$</td> <td>$[a, +\infty)$</td> </tr> <tr> <td>$\{x \in \mathbb{R} \mid x > a\}$</td> <td>$(a, +\infty)$</td> </tr> <tr> <td>$\{x \in \mathbb{R} \mid x \leq a\}$</td> <td>$(-\infty, a]$</td> </tr> <tr> <td>$\{x \in \mathbb{R} \mid x < a\}$</td> <td>$(-\infty, a)$</td> </tr> </tbody> </table> <p>When x and y are any two numbers either one of the following is true. $x > y$, $x < y$, $x = y$</p> <p>Results.</p> <p>When $a, b, c \in \mathbb{R}$</p> <p>(i) $a > b$ and $b > c \Rightarrow a > c$</p> <p>(ii) $a > b \Rightarrow a + c > b + c$</p> <p>(iii) $a > b$ and $c > 0 \Rightarrow ac > bc$</p> <p>(iv) $a > b > 0$ and $c < 0 \Rightarrow ac < bc$</p> <p>(v) $a > b$ and $c = 0 \Rightarrow ac = bc = 0$</p>	Interval	Notation	$\{x \in \mathbb{R} \mid a \leq x \leq b\}$	$[a, b]$	$\{x \in \mathbb{R} \mid a \leq x < b\}$	$[a, b)$	$\{x \in \mathbb{R} \mid a < x \leq b\}$	$(a, b]$	$\{x \in \mathbb{R} \mid a < x < b\}$	(a, b)	$\{x \in \mathbb{R} \mid x \geq a\}$	$[a, +\infty)$	$\{x \in \mathbb{R} \mid x > a\}$	$(a, +\infty)$	$\{x \in \mathbb{R} \mid x \leq a\}$	$(-\infty, a]$	$\{x \in \mathbb{R} \mid x < a\}$	$(-\infty, a)$	04
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		(vi) $a > b$ and $c > d \Rightarrow a + c > b + d$ (vii) $a > b > 0$ and $c > d > 0 \Rightarrow ac > bd$ (viii) $a > b > 0 \Rightarrow \frac{1}{a} < \frac{1}{b}$ (ix) $a < b < 0 \Rightarrow \frac{1}{a} > \frac{1}{b}$ (x) For $a > b > 0$ and n is a positive rational number, $a^n > b^n$ and $a^{-n} < b^{-n}$	
11.2	1. Solves inequalities involving polynomials.	When $f(x)$ and $g(x)$ are two polynomials of x inequalities such as, $f(x) \geq g(x)$, $f(x) > g(x)$ $f(x) \leq g(x)$, $f(x) < g(x)$ Linear functions, Quadratic functions are considered. Direct students to find the limit of values of x satisfying inequalities including linear, quadratic functions. Present the solutions using the inequality signs and set notation.	04
	2. Solves inequalities including rational functions.	Consider the rational functions, with the order less than or equal to two, in the denominator and the numerator.	
3.1	1. Introduces linear functions.	Introduce $f(x) = ax + b$, $a, b \in \mathbb{R}$, $a \neq 0$ as a linear function.	15
	2. Explains what a quadratic function is.	Recall that the function $f(x) = ax^2 + bx + c$ is called a quadratic function when $a \neq 0$ and $a, b, c \in \mathbb{R}$.	
	3. Explains the properties of a quadratic function.	Showing that the quadratic function can be written in the form $a(x + p)^2 + q$, $p, q \in \mathbb{R}$. Discuss the sign of the quadratic function for various values of x in terms of the above form. Show that the graph of the function is symmetrical about the line $x = -p$. Discuss the behaviour of the quadratic function,	

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	<p>4. Draws the graph of a quadratic function.</p> <p>5. Describes the different types of the graph of the quadratic function.</p>	<p>(i) When $\Delta > 0$, $a > 0$ and $a < 0$</p> <p>(ii) When $\Delta = 0$, $a > 0$ and $a < 0$</p> <p>(iii) When $\Delta < 0$, $a > 0$ and $a < 0$</p> <p>Here $\Delta = b^2 - 4ac$ is called the discriminant of the function $f(x) = ax^2 + bx + c$.</p> <p>Show that q is the maximum or the minimum value of the function, accordingly as a is positive or negative.</p> <p>Explain with examples existence or non-existence of real zeros.</p> <p>Direct students to draw the graphs of quadratic functions for the cases when $b^2 - 4ac > 0$, $b^2 - 4ac < 0$ and $b^2 - 4ac = 0$.</p> <p>Where $a > 0$, $a < 0$.</p> <p>Emphasises the properties of the quadratic function by means of the graphs drawn by students.</p> <p>$b^2 - 4ac > 0$ $a > 0$</p>  <p>$b^2 - 4ac = 0$ $a > 0$</p> 	

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3.2	1. Introduces what a quadratic equation is.	<p>State that when $a \neq 0$, $a, b, c \in \mathbb{R}$, $ax^2 + bx + c = 0$ which gives the zero points of the quadratic function is called the quadratic equation.</p>	15

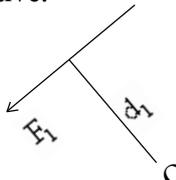
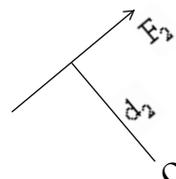
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	<p>2. Finds the roots of a quadratic equation.</p> <p>3. Describes the nature of the roots of a quadratic equation.</p> <p>4. Expresses the sum and product of the roots of quadratic equation in terms of its coefficient.</p> <p>5. Construct quadratic equations whose roots are symmetric functions of α and β.</p> <p>6. Solves problems involving quadratic functions and quadratic equations.</p>	<p>Prove that a quadratic equation cannot have more than two distinct roots.</p> <p>Prove that a quadratic equation in a single variable can have only two roots generally.</p> <p>If roots are α and β show that</p> $\alpha = \frac{-b - \sqrt{b^2 - 4ac}}{2a}, \quad \beta = \frac{-b + \sqrt{b^2 - 4ac}}{2a}$ <p>Accordingly as $b^2 - 4ac > 0$, $b^2 - 4ac = 0$ and $b^2 - 4ac < 0$, show that the roots of the quadratic equation are real and distinct or real and coincident or imaginary. Show the converse is also true.</p> <p>Explain that the necessary and sufficient condition for the roots of the quadratic equation to be real is $b^2 - 4ac \geq 0$, $\Delta = b^2 - 4ac$ is called the discriminant of the equation $ax^2 + bx + c = 0$.</p> <p>If the roots of the equation $ax^2 + bx + c = 0$ are α and β show that $\alpha + \beta = \frac{-b}{a}$ and $\alpha\beta = \frac{c}{a}$.</p> <p>If the roots of the equation $ax^2 + bx + c = 0$ are α and β obtain equations of whose roots are symmetric functions of α and β.</p> <p>Direct students to solve suitable problems.</p>	

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7	<p>1. Defines the exponential function (e^x).</p> <p>2. Expresses the domain and the range of the exponential function.</p> <p>3. States that e is an irrational number.</p> <p>4. Estimates the value of e.</p> <p>5. Describes the properties of the e^x.</p> <p>6. States that the exponential function too satisfies the laws of indices.</p> <p>7. Draws the graph of $y = e^x$</p> <p>8. Draws the graph of $y = e^{-x}$</p>	<p>State that the sum of the infinite series,</p> $1 + \frac{x}{1} + \frac{x^2}{2} + \frac{x^3}{3} + \dots + \frac{x^n}{n} + \dots$ <p>is denoted by e^x and that it is known as the exponential function.</p> <p>Here, since x is an exponent, e^x is referred as the exponential function.</p> <p>State if</p> $f(x) = e^x, \text{ then } D_f = \mathbb{R}, R_f = \mathbb{R}^+$ <p>e is the sum of the above infinite series when $x = 1$ and is a positive irrational number.</p> $f(1) = e = 1 + \frac{1}{1} + \frac{1}{2} + \frac{1}{3} + \dots + \frac{1}{n} + \dots = 2.718$ <p>Stress that e is a positive irrational number.</p> <p>State that</p> <p>(i) $e^0 = 1$</p> <p>(ii) $e^{(x_1+x_2)} = e^{x_1} \cdot e^{x_2}$</p> <p>(iii) $e^{(x_1-x_2)} = \frac{e^{x_1}}{e^{x_2}}$</p> <p>(iv) For rational values of r, $(e^x)^r = e^{rx}$</p> <p>(v) $\lim_{x \rightarrow \infty} e^x = \infty$</p> <p>(vi) $\lim_{x \rightarrow -\infty} e^x = 0$</p> <p>Deduce that e^x satisfies the laws of indices using the properties (i) and (ii) above.</p> <p>Present the graph of $y = e^x$. At this stage, the presentation of its shape is sufficient.</p> <p>Guide the students to draw the graph of $y = e^{-x}$.</p>	03

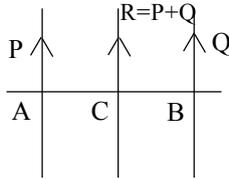
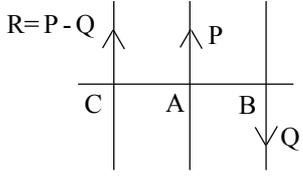
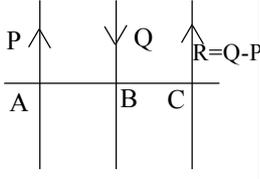
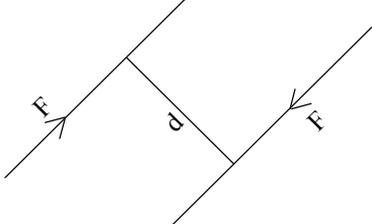
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	<p>9. Defines the natural logarithmic function.</p> <p>10. Expresses the domain and the range of the logarithmic function.</p> <p>11. Expresses the properties of $\ln x$.</p> <p>12. Draws the graph of $y = \ln x$.</p> <p>13. Defines the function a^x for $a > 0$.</p> <p>14. Expresses the domain and the range of $y = a^x$.</p>	<p>Explain that $\ln x$ defined as $y = \ln x \Leftrightarrow x = e^y$, $x \in \mathbb{R}^+$ is known as the natural logarithmic function.</p> <p>If $g(x) = \ln x$ then $D_g = \mathbb{R}^+$, $R_g = \mathbb{R}$</p> <p>(i) $\ln(xy) = \ln x + \ln y$ (ii) $\ln\left(\frac{x}{y}\right) = \ln x - \ln y$ (iii) $\ln(x^p) = p \ln x$; $x > 0, y > 0$</p> <p>Present the graph of $y = \ln x$. At this stage the shape of the graph alone is sufficient.</p> <p>The Function a^x is defined as $a^x = e^{x \ln a}$.</p> <p>If $h(x) = a^x$ $D_h = \mathbb{R}$ $R_h = \mathbb{R}^+$</p>	
19	Solves trigonometric equations	<p>(i) Equations of the form $\sin \theta = \sin \alpha$ $\cos \theta = \cos \alpha$ $\tan \theta = \tan \alpha$</p> <p>(ii) Equations that can be factorized.</p> <p>(iii) Equations that can be solved using Pythagorean identities, Addition formulae and Multiplication formulae.</p> <p>(iv) Equations that can be solved by assuming the formulae of double angles, triple angles or half angles.</p> <p>Solutions of equations that can be converted to the above forms are also expected. Also emphasize that equations of the form $a \cos \theta + b \sin \theta = c$ can also be solved.</p>	04

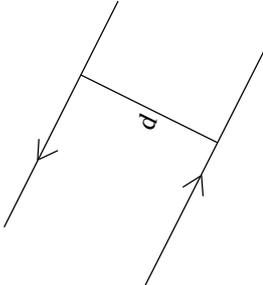
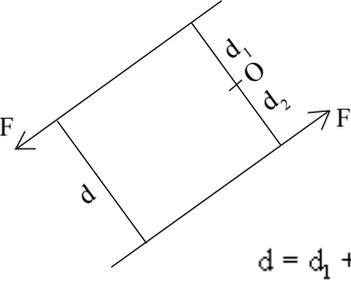
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20	<p>1. Defines inverse trigonometric functions.</p> <p>2. States the domain and the range of inverse trigonometric functions.</p> <p>3. Draws the graphs of inverse trigonometric functions.</p> <p>4. States simple relationships between inverse trigonometric functions.</p>	<p>(i) Explain that if $y = \sin x$, the value of x when y is given is stated as $x = \sin^{-1} y$ and that $x = \sin^{-1} y$ is not a function. But it can be made a function by limiting the domain of $y = \sin x$. Here, the domain of $\sin x$ generally limited as $-\frac{\pi}{2} \leq x \leq \frac{\pi}{2}$. The value of x for $\sin x$ are denoted as $x = \sin^{-1} y$. By interchanging x and y it can be denoted by $y = \sin^{-1} x$. Then $-\frac{\pi}{2} \leq \sin^{-1} x \leq \frac{\pi}{2}$.</p> <p>(ii) Explain similarly that $y = \cos^{-1} x$ is defined such that $0 \leq \cos^{-1} x < \frac{\pi}{2}$ and that $\tan^{-1} x$ is defined such that $-\frac{\pi}{2} < \tan^{-1} x < \frac{\pi}{2}$.</p> <p>(iii) Define, also, $y = \tan^{-1} x$ and explain that the values included in the domain $-\frac{\pi}{2} < x < \frac{\pi}{2}$ are its principal values.</p> <p>$y = \sin^{-1} x$; Domain $\left[-\frac{\pi}{2}, \frac{\pi}{2}\right]$, Range $[-1, 1]$. $y = \cos^{-1} x$; Domain $[0, \pi]$, Range $[-1, 1]$. $y = \tan^{-1} x$; Domain $\left(-\frac{\pi}{2}, \frac{\pi}{2}\right)$, Range $(-\infty, \infty)$.</p> <p>Draw the graphs of the functions $y = \sec^{-1} x$, $y = \operatorname{cosec}^{-1} x$ and $y = \cot^{-1} x$. State their domain and the range.</p> <p>Draw the graphs of these functions.</p> <p>Direct students to solve problems involving inverse trigonometric functions.</p>	06

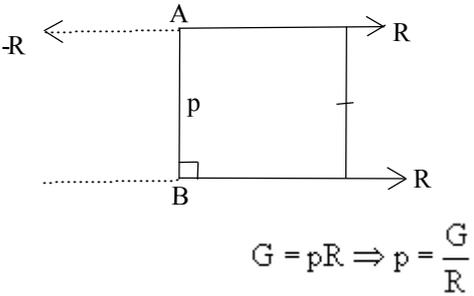
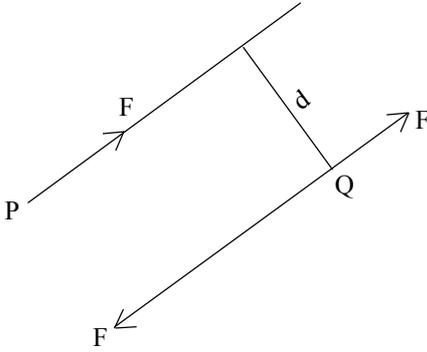
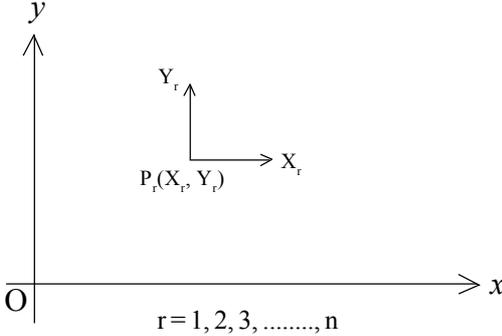
Combined Maths II

Com. Level	Learning Outcomes	Guidelines for Subject Matter	No. of Periods
2.4	<ol style="list-style-type: none"> 1. Describes a rigid body. 2. States the principle of transmission of forces. 3. Explains the translation and rotation of a force. 4. Defines the moment of a force about a point. 5. Explains the physical meaning of moment. 6. Finds the magnitude of the moment about a point and its sense. 	<p>Describe a rigid body as one in which the distance between any two points remains unchanged when it is subjected to external forces of any magnitude.</p> <p>Explain that a force acting on a rigid body can be considered to act at any point on its line of action.</p> <p>Show that a linear motion as well as a rotation can be created by a force.</p> <p>Present the definition that the moment of the force about a point is the product of the magnitude of the force and the perpendicular distance to its line of action from the given point.</p> <p>Build up the concept of moment as a measure of tendency to rotate about a certain point as a result of an external force acting on a rigid body. (For two dimensions only).</p> <p>Make them realise that what is measured by moment is a turning effect about a line perpendicular to the plane determined by that point and the line of action of the force</p> <p>Demonstrate that the sense of the moment can be considered as clockwise or anticlockwise. Explain that according to sign convention an anticlockwise moment is considered positive and a clockwise moment is considered negative.</p> <div style="text-align: center;">  <p>Moment of F_1 about $O = F_1 \times d_1$.</p>  <p>Moment of F_2 about $O = F_2 \times d_2 = -F_2 d_2$</p> </div>	04

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2.5	<p>7. States the dimensions and units of moments.</p> <p>8. Represents the magnitude of the moment of a force about a point geometrically.</p> <p>9. Determines the algebraic sum of the moments of the forces about a point in the plane of a coplanar system of forces.</p> <p>10. States the general principle of moment of a system of forces.</p> <p>1. Finds the resultant of two forces acting on a rigid body.</p>	<p>Show that dimension is ML^2T^{-2} and the unit is NM.</p> <p>Explain that the magnitude of the moment of a force F denoted in magnitude, direction and position by \vec{AB} about a point is twice the area of the triangle OAB.</p> <p>Direct students to solve problems of finding the algebraic sum of the moments of a system of coplanar forces about a point of the plane.</p> <p>State that the algebraic sum of moments of a system of coplanar forces about a point in the plane is equal to the moment of the resultant of the system about the same point. (Proof is not expected). Explain using suitable examples.</p> <ul style="list-style-type: none"> • When the two forces are not parallel As the two forces meet at a point show that their resultant can be determined by applying the law of parallelogram of forces. • When the two forces are parallel Introduce that forces acting on lines parallel to each other are known as parallel forces. <p>When two parallel forces are acting in the same direction they are said to be like forces, while those acting in opposite directions are said to be unlike forces.</p> <p>Explain that the parallelogram law of forces cannot be used to find the resultant of two parallel forces.</p> <p>If the two forces are P and Q and their resultant is R, and if the lines of action of P, Q and R intersect a certain straight line at A, B and C respectively.</p> <p>$R = P + Q$, if P and Q are like $R = P - Q$, ($P > Q$) if P and Q are unlike.</p>	04

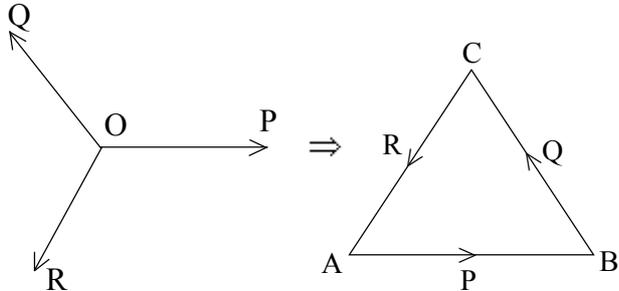
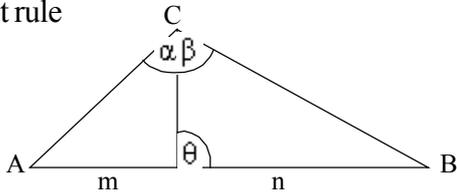
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	<p>2. States the conditions necessary for the equilibrium of two forces acting on a rigid body.</p> <p>3. Describes a couple.</p> <p>4. Calculates the moment of a couple</p>	<div style="display: flex; justify-content: space-around; align-items: flex-start;"> <div style="text-align: center;">  </div> <div style="text-align: center;">  </div> </div> <p style="text-align: center;">$P \cdot AC = Q \cdot CB$ When $P < Q$</p> <div style="display: flex; justify-content: center; align-items: center;">  </div> <p>Show that for two forces acting on a rigid body are in equilibrium, the two forces should be collinear, equal in magnitude and opposite in direction.</p> <p>Introduce a couple as a pair of parallel unlike (opposite) forces of equal magnitude. In this case, show that the vector sum of the two forces is zero, the algebraic sum of the moments of the two forces about any point is not zero. Therefore there is no translation, but only a rotation of the body.</p> <p>Show that the moment of a couple about any point in the plane of the couple is the product of the magnitude of one of the forces forming the couple and the perpendicular distance between the lines of action of the two forces.</p> <p>Mention that according to sign convention the anticlockwise (left handed) moments are considered as positive whereas clockwise (right handed) moments are considered to be negative.</p> <div style="text-align: center;">  </div> <p>Moment of the couple = $F \times d$ = $-F \times d$</p>	

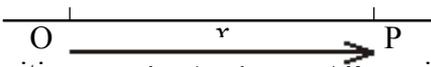
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	<p>5. States that the moment of a couple is independent of the point about which the moment of the forces is taken.</p> <p>6. States the necessary conditions for two coplanar couples to be equivalent</p> <p>7. States the conditions for two coplanar couples to balance each other.</p> <p>8. Combines coplanar couples</p>	 <p>Moment of the couple = $F \times d$</p>  <p>$d = d_1 + d_2$</p> <p>The moment of two forces about</p> $= Fd_1 + Fd_2 = F(d_1 + d_2)$ $= F \times d$ <p>Show that the same result will be obtained by taking moments about any point in the plane of the couple.</p> <p>As two coplanar couples with moments of equal magnitude and same sense produce same rotation, they are equivalent.</p> <p>As the resulting rotation when two coplanar couples of equal magnitude but of opposite sense, produce zero rotation, two such couples are said to balance each other.</p> <p>Explain that the algebraic sum of moment should be taken in finding the moment of the combination of two or more coplanar couples.</p>	

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2.6	<p>1. Reduces a couple and a single force acting in its plane into a single force.</p> <p>2. Shows that a force acting at a point is equivalent to the combination of an equal force acting at another point together with a couple.</p> <p>3. Reduce a system of coplanar forces to a single force acting at an arbitrary point O and a couple G.</p>	<div style="text-align: center;">  <p style="text-align: center;">$G = pR \Rightarrow p = \frac{G}{R}$</p> </div> <p>Show that a couple of moment G and a single force R acting in its plane is equivalent to a force equal and parallel to a force R acting at a distance $\frac{G}{R}$ from the point of action of it.</p> <p>Show that the force F acting at P is equivalent to the combination of a force F acting at a point Q and a couple of moment $G = F \times d$, where d distance between the lines of action of the two forces F.</p> <div style="text-align: center;">  </div> <p>Show how a system of coplanar force is reduced to a single force R acting at origin O and a couple of moment G</p> <div style="text-align: center;">  <p style="text-align: center;">$r = 1, 2, 3, \dots, n$</p> </div>	10

Com. Level	Learning Outcomes	Guidelines for Subject Matter	No. of Periods
	<p>4. Reduces any coplanar system of forces to a single force and a couple acting at any point in that plane.</p>	<p>Consider the system of coplanar forces F, acting at $P_r(X_r, Y_r)$. Where $r = 1, 2, \dots, n$ $\underline{R} = \sum_{r=1}^n \underline{E}_r = \sum_{r=1}^n (X_r \underline{i} + Y_r \underline{j})$ $= \left(\sum_{r=1}^n X_r \right) \underline{i} + \left(\sum_{r=1}^n Y_r \right) \underline{j}$ $= X \underline{i} + Y \underline{j}$ Where $X = \sum_{r=1}^n X_r$ and $Y = \sum_{r=1}^n Y_r$ Magnitude of R $R = \sqrt{X^2 + Y^2}$ If R makes an angle θ with the x-axis $\theta = \tan^{-1} \frac{Y}{X}$ and $G = \sum_{r=1}^n (x_r Y_r - y_r X_r)$ anti clockwise.</p> <p>Show how it can be reduced to a single force R' acting at the point $P(x, y)$ in the plane and a couple G' obtain that, $R' = R$ and $G' = G - xY + yX = 0$</p> <p>Present the following necessary and sufficient conditions for two coplanar systems of forces to be equivalent.</p> <p>That when each system of forces is resolved separately along two axes Ox and Oy perpendicular to each other selected in the plane of the two systems of forces each algebraic sum of components of one system of forces is equal to the corresponding algebraic sum of the other system of forces.</p>	

Com. Level	Learning Outcomes	Guidelines for Subject Matter	No. of Periods
	<p>5. (i) Reduction of a system of coplanar forces to a single force when it reduces to a single force.</p> <p>(ii) Reduction of a system of forces to a couple.</p> <p>(iii) Expresses conditions necessary for equilibrium.</p> <p>6. Finds the magnitude, direction and the line of action of the resultant of a coplanar system of forces.</p>	<p>$X' = X$, $Y' = Y$, where X and Y are the algebraic sums of one system of forces along Ox and Oy and X', Y' are the algebraic sums of the other system of forces along the same axes.</p> <p>If the algebraic sum of the moments of the two systems of forces about any point (h, k) in the plane, are G_1' and G_2', $G_1' = G_2'$.</p> <p>When a system of coplanar forces is reduced to a single force $\underline{R} = (X\underline{i} + Y\underline{j})$ acting at the origin O and couple of moment G, discuss cases,</p> <p>(i) $\underline{R} \neq \underline{0}$ (i.e. at least one of X or Y should not be zero). Show that when $G = 0$ it is reduced to a single force through another point.</p> <p>(ii) Show that $\underline{R} = \underline{0}$ (i.e., $X = 0$ and $Y = 0$) and $G \neq 0 \Rightarrow$ couple of moments.</p> <p>(iii) If $\underline{R} = \underline{0}$ (i.e., $X = 0$ and $Y = 0$) and $G = 0$. Show that the systems of forces are in equilibrium. Give suitable examples for each condition.</p> <p>Magnitude of the resultant $\underline{R} = \sqrt{X^2 + Y^2}$.</p> <p>If θ is the angle made by R with the x-axis,</p> $\theta = \tan^{-1} \left(\frac{Y}{X} \right).$ <p>Show that the equation of the line of action is $G - xY + yX = 0$.</p>	
2.7	1. States conditions for the equilibrium of three coplanar forces acting on a rigid body.	(i) If three co-planar forces acting on a rigid body are in equilibrium then their lines of action pass through the same point or else they are parallel. Explain that this is a necessary condition only.	10

Com. Level	Learning Outcomes	Guidelines for Subject Matter	No. of Periods
		<p>(ii) State again the law of triangle of forces and its converse. (This has been presented under the equilibrium of a particle.)</p>  <p>Three forces P, Q, R in equilibrium acting at O</p> <p>Corresponding triangle of forces, ABC.</p> <p>Using the triangle of forces - ABC, show that,</p> $\frac{P}{AB} = \frac{Q}{BC} = \frac{R}{CA}$ <p>use this result in solving problems.</p> <p>(iii) Lami's theorem (Presented under equilibrium of a particle)</p> <p>Explain that this theorem also can be applied in solving problems involving equilibrium of three coplanar non parallel forces whose line of action are concurrent.</p> <p>(iv) The algebraic sums of resolutes along two perpendicular directions separately are zero.</p> <p>(v) Cot rule</p>  $n \cot A - m \cot B = (m+n) \cot \theta \text{ or}$ $m \cot \alpha - n \cot \beta = (m+n) \cot \theta$ <p>Show that, using examples the above results can be used in solving problems.</p> <p>In solving problems make use of the geometrical properties of the diagram as far as possible.</p>	

Com. Level	Learning Outcomes	Guidelines for Subject Matter	No. of Periods
3.1	1. Defines “distance”. 2. States dimensions and standard units of distance. 3. Defines speed. 4. States dimensions and standard units of speed. 5. States that distance and speed are scalar quantities. 6. Defines average speed. 7. Defines instantaneous speed. 8. Defines uniform speed. 9. Defines position coordinates of a particle undergoing rectilinear motion.	<p>Distance: When a variable point P moves from a point A to a point B present the length measured along the path from A to B as the distance travelled by the point.</p> <p>Dimensions of distance : L Standard unit is m. Introduce other units of distance such as mm, cm, km.</p> <p>Speed:- Speed is defined as the rate of change of distance with respect to time.</p> <p>Dimension of speed LT^{-1}; Standard unit is $m s^{-1}$. Introduce other units of speed such as $km h^{-1}$.</p> <p>Distance is a quantity with a magnitude measured with some unit. Time is also same. Since they do not possess a direction demonstrate that distance and speed are scalar quantities.</p> <p>If the total distance travelled from A to B is s, and the time taken is t define that $\frac{s}{t}$ as the average speed during the time interval t.</p> <p>The speed of a moving particle at a given instant of time is defined as the instantaneous speed at that time.</p> <p>If the instantaneous speed of a particle over a certain time interval remains constant, define that speed as a uniform speed.</p> <div style="text-align: center;">  </div> <p>The position coordinate of a point P moving along a line ‘l’ is denoted by ‘x’, and defined as $x = \pm OP$ depending whether its position is on the right or left of the point O. Explain that x is a function of time t.</p>	10

Com. Level	Learning Outcomes	Guidelines for Subject Matter	No. of Periods
	10. Defines Displacement.	<p>Define displacement as the change in the position coordinate during a given time interval.</p> <p>If the position coordinate of the particle P at times t_1 and t_2 are x_1 and x_2 respectively, show that the displacement s of the particle during the time interval (t_1, t_2) is defined as $s = (x_2 - x_1)$.</p> <p>Explain that the displacement is a vector quantity. Show also that accordingly as $s > 0$ or $s < 0$ its direction is taken as \vec{s}.</p>	
	11. Expresses the dimension and standard units of displacement.	<p>Dimension L; Standard unit is m (meter)</p> <p>Explain other units too in terms of the standard units.</p>	
	12. Defines velocity.	<p>Velocity: Velocity is defined as the rate of change of displacement with respect to time.</p>	
	13. Expresses dimension and units of velocity.	<p>Dimension of velocity v is LT^{-1} and standard unit is ms^{-1}.</p> <p>Also explain other units in terms of the standard unit.</p>	
	14. Defines average velocity.	<p>If during the time interval (t_1, t_2) the displacement $s = (x_2 - x_1)$.</p> <p>Average velocity too is a vector quantity. Average velocity during that time interval is defined as $\frac{x_2 - x_1}{t_2 - t_1}$.</p> <p>The average velocity of a particle during a small interval $[t, t + h]$ is given by $= \frac{x(t+h) - x(t)}{h}$.</p>	
	15. Defines instantaneous velocity.	<p>Introduce this velocity as the instantaneous velocity of the particle at time 't'. Show that $v = \frac{ds}{dt}$ and explain that velocity is also a function of time.</p>	

Com. Level	Learning Outcomes	Guidelines for Subject Matter	No. of Periods
	<p>16. Defines uniform velocity.</p> <p>17. Draws the displacement time graph</p> <p>18. Finds the average velocity between two positions using the displacement time graph.</p> <p>19. Determines the instantaneous velocity between two positions using the displacement time graph.</p> <p>20. Defines acceleration</p>	<p>If the displacement 's' is measured from a fixed point O then show that v can also be written as $v = \frac{ds}{dt}$, i.e., velocity is the rate of change of displacement with respect to time. By convention, accordingly as $v > 0$ or $v < 0$, its direction is taken as \rightleftarrows.</p> <p>If the instantaneous velocity of some particle at any moment in some time interval is constant, then define the velocity of the particle in that time interval to be uniform.</p> <p>Using suitable examples provide an understanding of how displacement time graph is drawn.</p> <p>If s_1 and s_2 are the displacements corresponding to the times t_1 and t_2 show that the average velocity $\frac{s_2 - s_1}{t_2 - t_1}$ can be obtained by the gradient of the line P_1P_2. Here P_1 and P_2 are points on the displacement-time curve corresponding to times t_1 and t_2 respectively. Show that the gradient of the tangent drawn to the displacement time graph, at a particular point gives the instantaneous velocity at that moment. Obtain the relation, instantaneous velocity $= \frac{ds}{dt} = \text{gradient}$</p> <p>Show that the gradient of the tangent drawn to the displacement time graph, at a particular point gives the instantaneous velocity at that moment. Obtain the relation instantaneous velocity $= \frac{ds}{dt} = \text{gradient}$</p> <p>Acceleration: Define acceleration of the displacement-time curve at time t of the tangent as the rate of change of velocity with respect to time.</p>	

Com. Level	Learning Outcomes	Guidelines for Subject Matter	No. of Periods
	<p>21. Expresses the dimensions and units of acceleration.</p> <p>22. Defines average acceleration.</p> <p>23. Defines instantaneous acceleration.</p> <p>24. Defines uniform acceleration.</p> <p>25. Defines retardation.</p> <p>26. Draws the velocity time graph.</p>	<p>Express that the dimension of acceleration is LT^{-2} and the Standard unit is, meters per second (ms^{-2}). Mention other units of acceleration.</p> <p>If the velocities of a particle are v_1 and v_2 at times t_1 and t_2 respectively, then define the average acceleration of the particle during the time interval $[t_1, t_2]$ as $\frac{v_2 - v_1}{t_2 - t_1}$. Show that average acceleration ≥ 0 accordingly as $v_2 \geq v_1$</p> <p>The average acceleration during a small time interval $[t, t+h]$ is $\frac{v(t+h) - v(t)}{h}$. As $h \rightarrow 0$, the limit of the average acceleration = $\lim_{h \rightarrow 0} \frac{v(t+h) - v(t)}{h} = a$. Introduce a as the instantaneous acceleration at time t. Show that $a = \frac{dv}{dt}$. This is known as the acceleration of the particle at time t.</p> <p>Explain that acceleration is a function of time.</p> <p>Emphasize the fact that acceleration is the rate of change of velocity with respect to time.</p> <p>If the acceleration is constant in a certain time interval define that motion as a motion with uniform acceleration.</p> <p>State that when the acceleration is negative it is called a retardation.</p> <p>Provide an understanding of drawing velocity time graphs using suitable examples.</p>	

Com. Level	Learning Outcomes	Guidelines for Subject Matter	No. of Periods
	27. Finds average acceleration using the velocity time graph.	<p>If the velocities corresponding to times t_1 and t_2 are v_1 and v_2 respectively, then show that the average acceleration during the time interval $[t_1, t_2] = \frac{v_2 - v_1}{t_2 - t_1}$.</p> <p>It can be obtained as the gradient of the line P_1P_2. Here P_1 and P_2 are two points corresponding to times t_1 and t_2 in the velocity time curve.</p>	
	28. Finds the acceleration at a given instant using velocity - time graph.	<p>Show that the gradient of the tangent drawn at a given point to the velocity time graph gives the instantaneous acceleration at the time represented by the point. Deduce that instantaneous acceleration $a = \frac{dv}{dt}$ (gradient). Show also that $a = v \frac{dv}{ds}$.</p>	
	29. Finds displacement using velocity time graph.	<p>Explain that displacement during a certain time-interval is given by the area between the graph and the time axis. (an area below the time axis is assigned a negative sign).</p>	
	30. Draws velocity time graphs for different types of motion.	<p>Direct students to draw $v-t$ graphs for</p> <ol style="list-style-type: none"> 1. Position of rest - zero velocity. 2. Uniform velocity. 3. Uniform acceleration. 4. Uniform retardation. 5. A combinations of such motions. 	
	31. Solves problems using displacement time and velocity-time graph.	<p>Direct students to solve problems related to rectilinear motion with uniform acceleration.</p>	

Com. Level	Learning Outcomes	Guidelines for Subject Matter	No. of Periods
3.2	<p>1. Derives kinematic equations for a particle moving with uniform acceleration.</p> <p>2. Derives kinematic equations using velocity - time graph.</p> <p>3. Uses kinematic equations for vertical motion under gravity.</p> <p>4. Uses velocity - time and displacement - time graphs to solve problems related to vertical motion under gravity.</p>	<p>Introduce the standard symbols for initial velocity - u ; final velocity - v acceleration - a ; time - t and displacement - s and derive the kinematic equations.</p> $v = u + at$ $s = \frac{1}{2}(u + v)t$ $s = ut + \frac{1}{2}at^2$ $v^2 = u^2 + 2as$ <p>Guide students to derive kinematic equations using velocity-time graph.</p> <p>Show that in this case the acceleration should be replaced by g = (the acceleration due to gravity) which is a constant. Show that g is taken approximately as 10ms^{-2} and remind assumptions.</p> <p>Explain using suitable examples.</p>	08
3.3	<p>1. Describes the concept of frame of reference for one dimensional motion.</p> <p>2. Describes the motion of one body relative to the other when two bodies are moving on a straight line.</p>	<p>Introduce that a particle moving (on a straight line) and an axis fixed rigidly to the particle so that it lies along the line constitute a frame of reference.</p> <p>Explain with examples.</p>	07

Com. Level	Learning Outcomes	Guidelines for Subject Matter	No. of Periods
	<p>3. States the principle of relative displacement for two bodies moving along straight line.</p> <p>4. States the principle of relative velocity for two bodies moving along a straight line.</p> <p>5. States the principle of relative acceleration for two bodies moving along a straight line.</p> <p>6. Finds relative displacement, relative velocity and relative acceleration for two particles moving along two parallel paths.</p> <p>7. Uses kinematic equations and graphs related to motion for two bodies moving along the same straight line with constant relative acceleration.</p>	<p>If the displacement of particles P and Q relative to the frame of reference O on a straight line are $s_{P,O}$ and $s_{Q,O}$ respectively express the displacement of Q relative to P as $s_{Q,P} = s_{Q,O} + s_{O,P}$.</p> <p>Show that $s_{O,P} = -s_{P,O}$.</p> <p>Obtain $v_{Q,P} = v_{Q,O} + v_{O,P}$ by differentiating the displacement equation with respect to time.</p> <p>Obtain the relation $a_{Q,P} = a_{Q,O} + a_{O,P}$ by differentiating the velocity equation with respect to time.</p> <p>Explain using suitable examples.</p> <p>Consider only cases where the distance between the parallel paths is negligible.</p> <p>Guide students to solve related problems.</p>	

Combined Maths

Grade 12

Teacher's Instruction Manual

Third Term

Combined Maths I

Com. Level	Learning Outcomes	Guidelines for Subject Matter	No. of Periods
3.1	<p>1. Defines increment and incremental ratio.</p> <p>2. Discusses the existence of a derivative.</p>	<p>An infinitesimal change in a variable is called an increment. An increment change in x is usually denoted by Δx. Emphasize that Δx is a symbol and not the product of Δ and x.</p> <p>Let y be a function of x. Then x is called the independent variable and y the dependent variable. Let the increment in x be Δx and the corresponding increment in y be Δy.</p> <p>When x_0 is an element in the domain of $y = f(x)$ then $\frac{f(x_0 + \Delta x) - f(x_0)}{\Delta x}$ is called the increment ratio at $x = x_0$.</p> <p>When x_0 belongs to the range of x.</p> <p>If the above incremental ratio approaches a finite limit as $\Delta x \rightarrow 0$, then the function f is said to be differentiable with respect to x at $x = x_0$. This finite limit is called the derivative of f at $x = x_0$ or the differential coefficient of f with respect to x.</p> <p>It is denoted by the symbols $f'(x_0)$ or $\left[\frac{d}{dx}(f(x)) \right]_{x=x_0}$ or $\left(\frac{d}{dx} \right)_{x=x_0}$.</p> $f'(x_0) = \lim_{\Delta x \rightarrow 0} \frac{f(x_0 + \Delta x) - f(x_0)}{\Delta x}$ <p>Using suitable examples, explain that the derivative of $f(x)$ does not exist at $x = x_0$ in the instances given below.</p> <p>(i) When f is not defined in an open interval including $x = x_0$.</p> <p>(ii) When the $\lim_{\Delta x \rightarrow 0} \frac{f(x_0 + \Delta x) - f(x_0)}{\Delta x}$ does not exist.</p>	04

Com. Level	Learning Outcomes	Guidelines for Subject Matter	No. of Periods
23.2	3. Defines the derivative function.	<p>(iii) When the limit $\lim_{\Delta x \rightarrow 0} \frac{f(x_0 + \Delta x) - f(x_0)}{\Delta x}$ is not finite. Explain these, using examples.</p> <p>Let f be a function of x. If the derivative of f exists at some point x, the function f' whose domain consists of all such x values is called the derivative function of x.</p> <p>That is $(f')(x) = f'(x)$</p> <p>It is denoted by $\frac{df(x)}{dx}$ or $\frac{dy}{dx}$</p> <p>When $y = f(x)$</p> <p>$\therefore f'(x) = \frac{df(x)}{dx} = \frac{dy}{dx}$.</p>	05
	4. Represents the derivative geometrically.	<p>Explain that the derivative represent the gradient of the tangent at $P(x, y)$ to the graph of the function $y = f(x)$.</p>	
	1. Differentiates a function from first principles.	<p>When n is a rational number, showing the method of determining the derivative of x^n and the derivatives of basic trigonometric functions from first principles present the proofs of the following results.</p> $\frac{d}{dx}(x^n) = n x^{n-1} \quad \frac{d}{dx}(\cot x) = -\operatorname{cosec}^2 x$ $\frac{d}{dx}(\sin x) = \cos x \quad \frac{d}{dx}(\sec x) = \sec x \tan x$ $\frac{d}{dx}(\cos x) = -\sin x \quad \frac{d}{dx}(\operatorname{cosec} x) = -\operatorname{cosec} x \cot x$ $\frac{d}{dx}(\tan x) = \sec^2 x$	

Com. Level	Learning Outcomes	Guidelines for Subject Matter	No. of Periods
23.3	<p>1. States fundamental results of derivatives.</p> <p>2. Solves problems using fundamental results of derivatives.</p> <p>3. States the results of derivatives of a product, quotient and a composite function.</p>	<p>Prove that</p> <p>(i) When k is a constant and $f(x) = k$ then $f'(x) = 0$.</p> <p>(ii) If $f(x) = kg(x)$ then $f'(x) = kg'(x)$.</p> <p>(iii) If $f(x) = g(x) \pm h(x)$ then $f'(x) = g'(x) \pm h'(x)$</p> <p>Direct students to solve problems using $\frac{d(x^n)}{dx} = nx^{n-1}$ and the above theorems after explaining suitable examples.</p> <p>(i) $\frac{d}{dx} [f(x) \cdot g(x)] = f(x) \frac{d}{dx} [g(x)] + g(x) \frac{d}{dx} [f(x)]$</p> <p>(ii) $\frac{d}{dx} \left[\frac{f(x)}{g(x)} \right] = \frac{g(x) \frac{d}{dx} [f(x)] - f(x) \frac{d}{dx} [g(x)]}{\{g(x)\}^2}$, $g(x) \neq 0$</p> <p>(iii) If y is a function of u and u is a function of x then $\frac{dy}{dx} = \frac{dy}{du} \cdot \frac{du}{dx}$ (Chain Rule) and its extension. Present the above results. Proofs are not required.</p>	05

Com. Level	Learning Outcomes	Guidelines for Subject Matter	No. of Periods
24.1	<p>4. Finds the derivatives of fundamental trigonometric functions.</p> <p>1. Obtains the derivatives of inverse circular functions.</p> <p>2. Solves problems using the derivatives of inverse circular functions.</p> <p>3. Writes the derivative of the exponential function.</p> <p>4. Solves problems using the derivative of the exponential function.</p> <p>5. Deduces the derivative of $(\ln x)$</p> <p>6. Deduces the derivative of a^x.</p> <p>7. Solves problems using the derivatives of $\ln x$ and a^x.</p>	<p>State that these should be memorized as standard results. Direct students to solve a variety of problems using these results.</p> <p>Deduces that</p> <p>(i) $\frac{d}{dx}(\sin^{-1} x) = \frac{1}{\sqrt{1-x^2}}, -1 < x < 1$</p> <p>(ii) $\frac{d}{dx}(\cos^{-1} x) = \frac{-1}{\sqrt{1-x^2}}, -1 < x < 1$</p> <p>(iii) $\frac{d}{dx}(\tan^{-1} x) = \frac{1}{1+x^2}, -\infty < x < \infty$</p> <p>Differentiates various functions using the above formula.</p> <p>State that $\frac{de^x}{dx} = e^x$</p> <p>Direct students to solve relevant problems.</p> <p>Deduce that $\frac{d(\ln x)}{dx} = \frac{1}{x}, x > 0$ derivative of $(\ln x)$</p> <p>Deduces that $\frac{d(a^x)}{dx} = (\ln a)a^x$.</p> <p>Present examples and give exercises.</p>	03

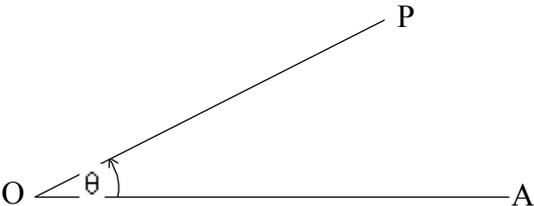
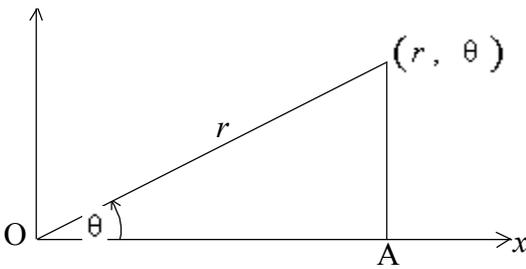
Com. Level	Learning Outcomes	Guidelines for Subject Matter	No. of Periods
23.5	1. Defines implicit functions. 2. Determines the derivatives of implicit functions. 3. Differentiates parametric functions.	<p>Presenting various equations of the form $F(x, y) = 0$ in variables x and y show that if y be made the subject there may be more than one answer for y in terms of x, if a suitable domain is selected, in some cases, y is a function of x. These functions determined by an equation of the form $F(x, y) = 0$ are called implicit functions.</p> <p>Show separately the derivatives of each implicit function obtained from an equation in x and y of the form $F(x, y) = 0$. Then show that all the above derivatives can be obtained at once, by differentiating the original equation with respect to x.</p> <p>When x and y are differentiable functions of the parameter “t”</p> $\frac{dy}{dx} = \frac{\frac{dy}{dt}}{\frac{dx}{dt}}; \quad \frac{dx}{dt} \neq 0$ <p>Then $\frac{dy}{dx}$ is a function of parameter t. Show that</p> $\frac{d^2y}{dx^2} = \frac{\frac{d}{dt} \left(\frac{dy}{dx} \right)}{\frac{dx}{dt}}; \quad \frac{dx}{dt} \neq 0$	03
23.6	1. Determines derivatives of higher order. 2. Differentiates functions of various types.	<p>When y is a function of x then n^{th} order differential of y is obtained by differentiating y with respect to x, n times. This is denoted by $\frac{d^n y}{dx^n}$ or $f^{(n)}(x)$ or $y^{(n)}$</p> <p>Direct the students to solve various types of problems using the above results.</p>	03

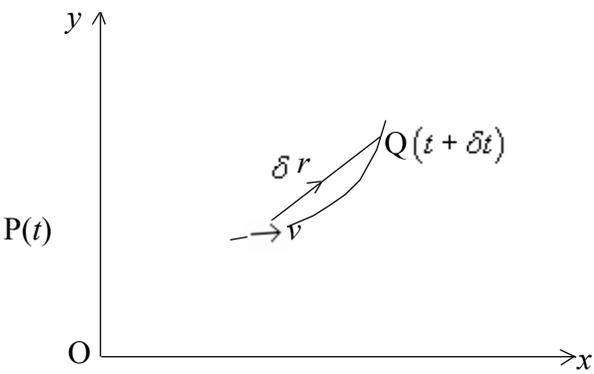
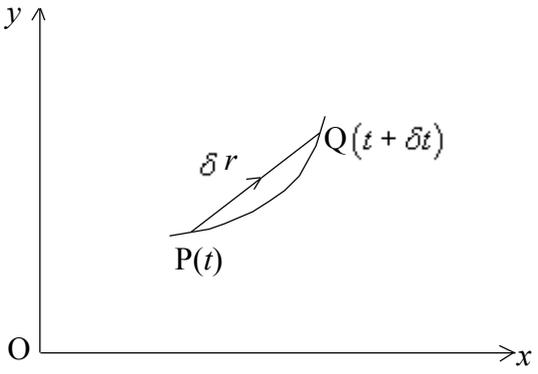
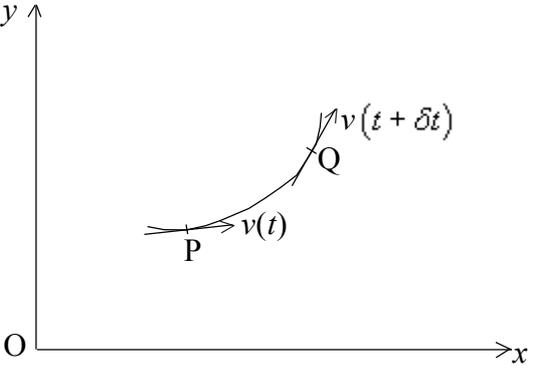
Com. Level	Learning Outcomes	Guidelines for Subject Matter	No. of Periods
24.1	<p>1. Defines average rate and instantaneous rate.</p> <p>2. States that velocity and acceleration are the derivatives, with respect to time, of displacement and velocity respectively.</p> <p>3. Differentiates between increasing and decreasing functions.</p>	<p>When $y = f(x)$, $y_1 = f(x_1)$ and $y_2 = f(x_2)$, $\frac{y_2 - y_1}{x_2 - x_1} = \frac{f(x_2) - f(x_1)}{x_2 - x_1}$ is called the average rate of change in y' with respect to x when the variable x is changing from x_1 to x_2.</p> <p>If $x_2 = x_1 + \Delta x$, then the instantaneous rate of change in y with respect to x at the instant $x = x_1$ is defined as</p> $f'(x_1) = \lim_{\Delta x \rightarrow 0} \frac{f(x_1 + \Delta x) - f(x_1)}{\Delta x}.$ <p>The displacement s of moving particle is a function of the time t. The instantaneous rate of change, $\frac{ds}{dt}$, of s with respect of the time t is defined as the velocity (v) of the particle at t. The velocity v of a moving particle is also a function of the time t. The instantaneous rate of change, $\frac{dv}{dt}$, of v with respect to the time t is defined as the acceleration (a) of the particle.</p> <p>If for all $x_1, x_2 \in [a, b]$ when $x_1 < x_2$ if $f(x_1) < f(x_2)$ then f is said to be an increasing function in $[a, b]$.</p> <p>If for all $x_1, x_2 \in [a, b]$ when $x_1 < x_2$ if $f(x_1) \leq f(x_2)$ then f is said to be a non decreasing function in $[a, b]$.</p> <p>If for all $x_1, x_2 \in [a, b]$ when $x_1 < x_2$ if $f(x_1) > f(x_2)$ then f is said to be a decreasing function in $[a, b]$.</p> <p>If for all $x_1, x_2 \in [a, b]$ when $x_1 < x_2$ if $f(x_1) \geq f(x_2)$ then f is said to be a non increasing function in $[a, b]$.</p>	03

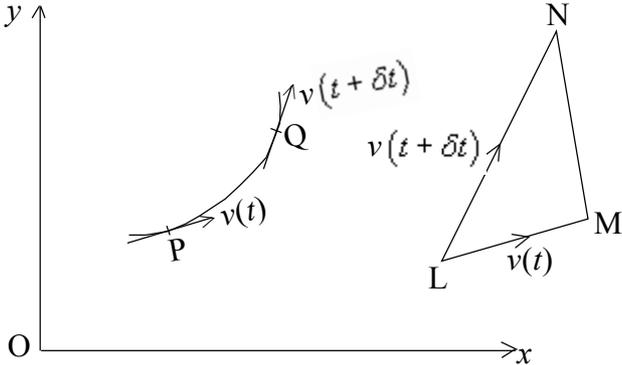
Com. Level	Learning Outcomes	Guidelines for Subject Matter	No. of Periods
24.2	<p>4. Determines the behaviour of a function in an interval using derivatives.</p> <p>Writes down the equations of the tangent and normal at a given point to a curve.</p>	<p>Explain the determination of increasing or decreasing functions within an interval using the derivatives of the function. State that the condition necessary for the function $Y = f(x)$, for any $x \in [a, b]$ is $\frac{dy}{dx} > 0$. Convince by a diagram. State the corresponding condition for decreasing functions too.</p> <p>Consider the function f defined for an open interval that includes x_1. Let m denote $\lim_{\Delta x \rightarrow 0} \frac{f(x_1 + \Delta x) - f(x_1)}{\Delta x}$ if it exists. Then m is called the gradient of the tangent of the curve $y = f(x)$ at the point (x_1, y_1). Equation of the tangent is $y - y_1 = m(x - x_1)$. And show that the gradient of the normal is $-\frac{1}{m}$ and the equation of the normal is $y - y_1 = -\frac{1}{m}(x - x_1)$. When $m \neq 0$, $\frac{1}{m}$ is called the gradient of the normal and the equation of the normal therefore, $y - y_1 = \frac{1}{m}(x - x_1)$.</p>	03
24.3	<p>1. Defines stationary points on a given function.</p> <p>2. Describes what a relative maximum and a relative minimum.</p> <p>3. Employs the first derivative test to find the maximum and minimum points of a function.</p>	<p>In a differentiable function defined $x = c$, such that $f'(c) = 0$, is define as a stationary point. Explain with suitable example.</p> <p>If a function f defined at $x = c$, is differentiable at $x = c$ and if then the point where $x = c$ defined as a critical point. Show that, if for $x \in (a - \theta, a + \theta)$ there exists $\theta > 0$ such that $f(a) \leq f(b)$, then f is said to have a relative minimum at $x = a$.</p> <p>Describe the 1st derivative test. Present the first derivative test.</p>	03

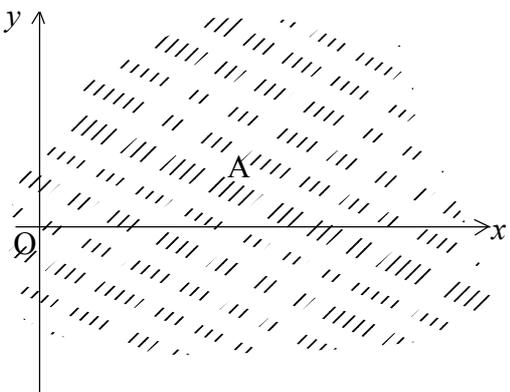
Com. Level	Learning Outcomes	Guidelines for Subject Matter	No. of Periods
	<p>4. States that there exists critical points, which are neither a local maximum nor a local minimum.</p> <p>5. Uses the second differential coefficient to test whether a turning point in a given function is a local maximum or a local minimum</p>	<p>Discuss the examples, cases in which, even though $f'(c) = 0$, the point where $x = c$ is neither a relative maximum nor a relative minimum.</p> <p>If $f'(a) = 0$ and $f''(a) > 0$, there is a minimum at $x = a$.</p> <p>If $f'(a) = 0$ and $f''(a) < 0$ there is a maximum at $x = a$.</p>	
24.4	Sketches the graph of function.	<p>Direct the students to draw graphs of function using the above principles.</p> <p>Examples involving horizontal and vertical asymptotes are also included.</p>	03
24.5	Uses derivatives to solve day-to-day problems.	Direct students to solve problems involving maximum and minimum in day-to-day activities.	05
9	<p>1. Identifies mathematical induction as a method of logical proof.</p> <p>2. Uses the method of mathematical induction to solve problems.</p>	<p>Introduce Mathematical induction as a method of proving a mathematical result depending on “n” positive integers step by step logically.</p> <p>Introduce the following step used in mathematical induction.</p> <p>(i) Show the result is true when $n = 1$.</p> <p>(ii) Assuming that the result is true when $n = p$ (a positive integer) and prove that the result is true when $n = p + 1$</p> <p>(iii) Finally state that the result is true for all positive integers which n can take..</p> <p>Give the exercises with examples.</p>	05

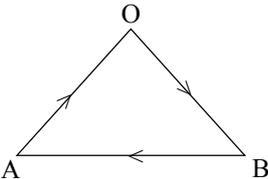
Combined Maths II

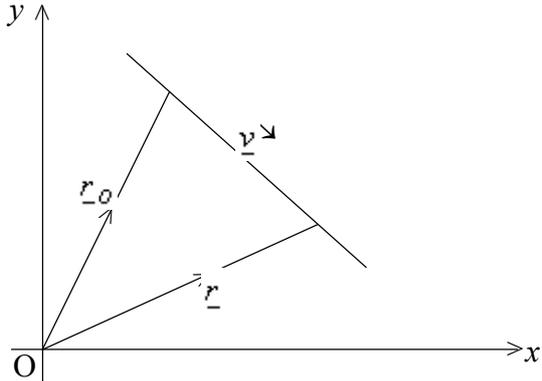
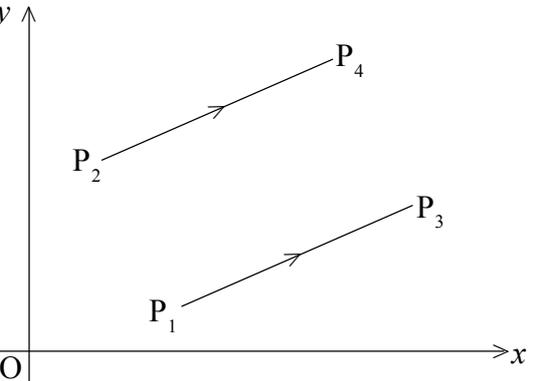
Com. Level	Learning Outcomes	Guidelines for Subject Matter	No. of Periods
3.4	<p>1. Introduces the system of polar coordinates.</p> <p>2. Derives the relation between polar co-ordinates and cartesian coordinates.</p> <p>3. Expresses the position of a particle in vectors.</p>	<div style="text-align: center;">  </div> <p>If O is a fixed point through O, OA is a fixed line and P is a variable point such that $OP = r$ and $\angle AOP = \theta$, then state that the polar coordinates of P are defined as (r, θ). Here $r \geq 0$, and the angle θ measured anticlockwise is taken to be positive. Show that a point can also be denoted uniquely by polar co-ordinates.</p> <div style="text-align: center;">  </div> <p>With respect to the system of axes Oxy if $P \equiv (x, y)$ derive that $x = r \cos \theta$, $y = r \sin \theta$.</p> <p>Then show that $\underline{r} = x\underline{i} + y\underline{j}$</p> $\Rightarrow \underline{r} = r(\cos \theta \underline{i} + \sin \theta \underline{j})$ <p>Consider a system of coordinate axes Oxy in the plane of the motion of particle P. Take unit vectors along Ox and Oy as \underline{i} and \underline{j} respectively. Then if (x, y) are the position coordinates of P the position vector of P is given by $\underline{r} = x\underline{i} + y\underline{j}$.</p> <p>Show that x and y are functions of time.</p> <p>Then $\underline{r} = x(t)\underline{i} + y(t)\underline{j}$.</p>	06

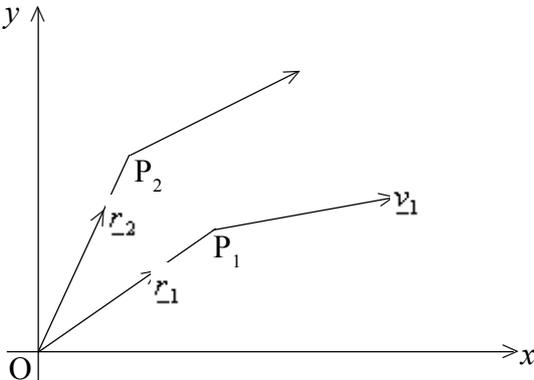
Com. Level	Learning Outcomes	Guidelines for Subject Matter	No. of Periods
	<p>4. Introduces the average velocity of a particle moving on a plane.</p> <p>5. Defines instantaneous velocity.</p> <p>6. Defines the average acceleration of a particle moving on a plane.</p>	<div style="text-align: center;">  </div> <p>Take the position of a point at time t relative to the origin O as P and its position at time $t + \delta t$ as Q. Here, if $\overrightarrow{OP} = \underline{r}$. Show that the average velocity in the time interval δt can be expressed as $\frac{\overrightarrow{PQ}}{\delta t} = \frac{\delta \underline{r}}{\delta t}$.</p> <div style="text-align: center;">  </div> <p>State that the instantaneous velocity of the particle at time t is defined as $\underline{v} = \lim_{\delta t \rightarrow 0} \frac{(\underline{r} + \delta \underline{r}) - \underline{r}}{\delta t} = \lim_{\delta t \rightarrow 0} \frac{\delta \underline{r}}{\delta t} = \frac{d\underline{r}}{dt}$</p> <div style="text-align: center;">  </div>	

Com. Level	Learning Outcomes	Guidelines for Subject Matter	No. of Periods
	7. Defines the instantaneous acceleration of a particle moving on a plane	<p>State that the position of the particle at time t is P and the velocity is $\underline{v}(t + \delta t)$.</p> <p>Define the average acceleration of the particle in the time interval δt is equal to $\frac{\underline{v}(t + \delta t) - \underline{v}(t)}{\delta t}$.</p> <p>The instantaneous acceleration of a particle at time t is defined as</p> $\underline{a} = \lim_{\delta t \rightarrow 0} \frac{\underline{v}(t + \delta t) - \underline{v}(t)}{\delta t}$ $= \lim_{\delta t \rightarrow 0} \frac{\delta \underline{v}}{\delta t} = \frac{d\underline{v}}{dt}$ <p>The direction of the acceleration</p>  <p>If the velocity $\underline{v}(t)$ at time t is represented by \overline{LM} and the velocity $\underline{v}(t + \delta t)$ at time $t + \delta t$ by \overline{LN} (in magnitude and direction), then \overline{MN} represents $\underline{v}(t + \delta t) - \underline{v}(t)$.</p> <p>Emphasize that as $\lim_{\delta t \rightarrow 0} \frac{\underline{v}(t + \delta t) - \underline{v}(t)}{\delta t}$ gives the acceleration, \overline{MN} gives the direction of the acceleration as $\delta t \rightarrow 0$, i.e., the acceleration of the particle is directed towards the concave side of its path.</p>	

Com. Level	Learning Outcomes	Guidelines for Subject Matter	No. of Periods
	<p>8. Finds velocity \underline{v} when the position vector is given as a function of time.</p>	<p>The instantaneous velocity</p> $\underline{v} = \frac{dx}{dt} \underline{i} + \frac{dy}{dt} \underline{j}$ $= [\dot{x} \underline{i} + \dot{y} \underline{j}]$ <p>Remind that \underline{i} and \underline{j} are constant unit vectors.</p> <p>Express that, if $\frac{dx}{dt} = \dot{x}$ and $\frac{dy}{dt} = \dot{y}$</p> <p>\underline{v} can be written as $\underline{v} = \dot{x} \underline{i} + \dot{y} \underline{j}$.</p> <p>Show that the magnitude of the instantaneous velocity</p> $= \sqrt{\dot{x}^2 + \dot{y}^2}$ <p>and its direction is given by $\tan \theta = \frac{\dot{y}}{\dot{x}}$</p> <p>where θ is the angle made by the direction of the velocity with the positive direction of the x-axis. Explain also that the magnitude of the velocity is known as its speed and its direction is along the tangent at the point P to the curve of its path.</p>	
3.5	<p>9. Finds the acceleration when its position vector is given as a function of time.</p> <p>1. Describes the concept of frame of reference for two dimensional motion.</p>	<p>Express that, since $\underline{v} = \dot{x} \underline{i} + \dot{y} \underline{j}$, \underline{a} can be obtained as</p> $\underline{a} = \frac{d\underline{v}}{dt} = \frac{d}{dt} (\dot{x}) \underline{i} + \frac{d}{dt} (\dot{y}) \underline{j}$ $= \ddot{x} \underline{i} + \ddot{y} \underline{j}$ <p>Since only two dimensional motion is considered here, it is sufficient to consider a frame of reference as follows.</p> 	06

Com. Level	Learning Outcomes	Guidelines for Subject Matter	No. of Periods
	<p>2. Presents vectorially the terms displacement, velocity and acceleration relative to a frame of reference for two dimensional motion.</p> <p>3. Describe the (relative) motion of one particle relative to another.</p> <p>4. Express the principle of relative displacement.</p> <p>5. Expresses the principle of relative velocity.</p> <p>6. Expresses the principle of relative acceleration.</p> <p>7. Describes the velocity of one body relative to another body.</p>	<p>Consider a body A moving in a plane. Select Cartesian axes perpendicular to each other in the plane of motion and rigidly fixed to the body A. Introduce that a fixed set of points relative to the axes (can be extended at will) is known as the frame of reference of A.</p> <p>Remind the earlier definitions of displacement, velocity and acceleration. Explain that if the displacement of a particle relative to the origin of a frame of reference is \underline{r} then the velocity $\underline{v} = \frac{d\underline{r}}{dt}$ and the acceleration $\underline{a} = \frac{d\underline{v}}{dt}$.</p> <p>Explain using suitable examples.</p> <p>Show that if $\underline{r}_{A,O}$ and $\underline{r}_{B,O}$ are the position vectors of A and B respectively, relative to the origin O then the position vector of B relative to A, $\underline{r}_{B,A}$ is given by $\underline{r}_{B,A} = \underline{r}_{B,O} - \underline{r}_{A,O}$</p> <div style="text-align: center;">  </div> <p>$\underline{r}_{B,A} = \underline{r}_{B,O} - \underline{r}_{A,O}$ $\underline{r}_{B,A} = \underline{r}_{B,O} + \underline{r}_{O,A}$</p> <p>Derive the velocity of B relative to A, $\underline{v}_{B,A} = \underline{v}_{B,O} + \underline{v}_{O,A}$ by differentiating the displacement equation with respect to time.</p> <p>By differentiating the velocity equation with respect to time, derive that $\underline{a}_{B,A} = \underline{a}_{B,O} + \underline{a}_{O,A}$.</p> <p>Direct students to find the velocity of one body relative to another body when the relative velocity is uniform.</p>	

Com. Level	Learning Outcomes	Guidelines for Subject Matter	No. of Periods
3.6	<p>8. Determines the path of one body relative to another body using the principle of relative motion.</p> <p>Uses the principle given above to solve problems involving relative motion.</p>	<p>Direct students to find the path of one body relative to another body when the relative velocity is uniform.</p> <p>Direct the students to find the following when the relative velocity is uniform.</p> <ul style="list-style-type: none"> (i) The velocity of a body relative to another. (ii) The shortest distance between the two bodies and time taken to reach it. (iii) The time taken by two bodies to collide the condition for collision and position of collision. (iv) The time taken to complete a given path. (v) Present solutions of problems involving motions relative to water or air. 	10
3.7	<p>1. Finds the vector equation of a line on which a body is moving.</p> <p>2. Finds the position of two particles at any instant.</p>	 <p>Derive that the vector equation is $\underline{r} = \underline{r}_0 + \lambda \underline{v}$.</p>  <p>Show that the distance between the two particles at any instant when</p> $\overrightarrow{OP_4} = \underline{r}_1 + \underline{v}_1 t$ $\overrightarrow{OP_3} = \underline{r}_2 + \underline{v}_2 t$ <p>is given by $\overrightarrow{P_3P_4}$</p>	06

Com. Level	Learning Outcomes	Guidelines for Subject Matter	No. of Periods
	<p>3. Finds the relative position and the relative velocity of a particle using vectors.</p> <p>4. Finds the shortest distance between two particles and time taken to attain it.</p> <p>5. Finds the condition for impact of two particles, the position vector at the point of impact and the time for impact.</p> <p>6. Solves problems involving relative motion of three particles.</p>	 <p>Show that displacement $(P_2, P_1) = r_1 - r_2$ and velocity $(P_2, P_1) = v_1 - v_2$.</p> <p>As the distance between the two particles is a function of time direct the students to find the shortest distance and the time taken to attain it using differentiation.</p> <p>Show that the condition for impacts of the two particles is</p> <p>(i) $\overrightarrow{P_3P_4} = \underline{0}$ or</p> <p>(ii) $vel(\overrightarrow{P_2, P_1}) = \overrightarrow{P_2P_1}$</p> <p>Direct the students to find the time for impact and to find the position vector of the particles by using any one of the above conditions.</p> <p>Direct students to use vector methods to find the true motion of a particle (relative to the Earth) when the motion of the particle relative to two particles are known separately.</p>	

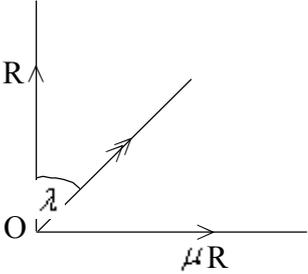
Com. Level	Learning Outcomes	Guidelines for Subject Matter	No. of Periods
3.8	<p>1. Introduces a projectile.</p> <p>2. Describes the terms “velocity of projection” and “angle of projection”</p> <p>3. State that the motion of a projectile can be considered as two motions, separately, in the horizontal and vertical directions.</p> <p>4. Applies the kinematic equations to interpret motion of a projectile.</p> <p>5. Calculates the components of velocity of a projectile after a given time.</p> <p>6. Finds the components of displacement of a projectile in a given time.</p> <p>7. Calculates the maximum height of a projectile.</p>	<p>Introduce a projectile as a particle or a body moving freely under gravity.</p> <p>When a particle or a body is projected with a velocity u inclined at an angle α to the horizontal introduce that u is the velocity of projection and α is the angle of projection.</p> <p>Explain that the velocity component is constant for the horizontal motion and the acceleration, which is that due to gravity, is constant for the vertical motion.</p> <p>Show that the following equations can be used with $a = g$,</p> <p>Horizontally $s = ut$ Vertically $v = u + at$</p> $s = ut + \frac{1}{2}at^2$ $v^2 = u^2 + 2a s$ <p>Derive that the horizontal and vertical components of velocity at a time t, are $\dot{x} = u \cos \alpha$ and $\dot{y} = u \sin \alpha - gt$.</p> <p>Derive that the components of displacement at time t as $x = (u \cos \alpha) \cdot t$ and $y = (u \sin \alpha) \cdot t - \frac{1}{2}gt^2$. State that these are parametric equations of the path of the projectile where “t” is the parameter.</p> <p>Show that if H is the maximum height, then</p> $H = \frac{u^2 \sin^2 \alpha}{2g}$	08

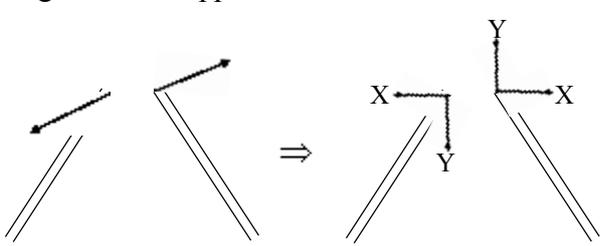
Com. Level	Learning Outcomes	Guidelines for Subject Matter	No. of Periods
	<p>8. The time taken to reach the maximum height of a projectile.</p> <p>9. Calculates the horizontal range of a projectile.</p> <p>10. Calculates the horizontal range of a projectile.</p> <p>11. State that in general there are two angles of projection for the same horizontal range for a given velocity of projection.</p> <p>12. Finds the maximum horizontal range for a given speed.</p> <p>13. For a given speed of projection finds the angle of projection giving the maximum horizontal range.</p> <p>14. Derives Cartesian equations of the path of a projectile.</p>	<p>Show that if T is the time taken to reach the maximum height, then $T = \frac{u \sin \alpha}{g}$.</p> <p>If T' is the time taken to return to the level of the point of projection. Then show that $T' = \frac{2u \sin \alpha}{g} = 2T$.</p> <p>If R is the horizontal range through the point of prejection derive the expression $R = \frac{2u^2}{g} \cos \alpha \sin \alpha$</p> <p>Show that there are two angles of projection giving the same value for R which is obtained when $\alpha = \theta$ and $\alpha = \frac{\pi}{2} - \theta$ are substituted in the the expression for the same horizontal range $R = \frac{2u^2}{g} \cos \alpha \sin \alpha$.</p> <p>As $R = \frac{u^2 \sin 2\alpha}{g} \leq \frac{u^2}{g}$ deduce that $R_{\max} = \frac{u^2}{g}$, for given u.</p> <p>Derive that the angle of projection giving the maximum horizontal range is $\frac{\pi}{4}$.</p> <p>Derive the equation $y = x \tan \alpha - \frac{gx^2 \sec^2 \alpha}{2u^2}$ by eliminating t from the equation obtained earlier for x and y when $\alpha \neq \frac{\pi}{2}$. Compare this with the familiar quadratic function $y = ax - bx^2$.</p> <p>Remind that $\alpha = \frac{\pi}{2}$ gives vertical motion under gravity.</p>	

Com. Level	Learning Outcomes	Guidelines for Subject Matter	No. of Periods
3.9	<ol style="list-style-type: none"> States Newton's first law of motion. Defines "force". Defines "mass". Defines linear momentum of a particle. States that linear momentum is a vector quantity. States the dimensions and unit of linear momentum. Describes an inertial frame of reference. States Newton's second law of motion. Defines Newton as the absolute unit of force. Derives the equation $\underline{F} = m\underline{a}$ from second law of motion. 	<p>A body continues to be in a state of rest, or of uniform motion along a straight line, unless it is acted upon by an external force.</p> <p>Define 'force' as the external action that changes the state of motion of a body.</p> <p>Define mass as the amount of response of the body to a force acting on it.</p> <p>Define linear momentum of a particle of mass m moving with a velocity u as mu.</p> <p>Show that in the product mu, the velocity is a vector and hence the linear momentum is also a vector.</p> <p>The dimensions of linear momentum are $[MLT^{-1}]$. Unit of linear momentum is $kgms^{-1}$.</p> <p>Describe an inertial frame of reference as a frame, which is at rest or moving with a uniform velocity relative to a frame of reference fixed on the earth. [Earth is considered as an inertial frame of reference in studying motions taking place on Earth's - surface.]</p> <p>The rate of change of linear momentum of a body is directly proportional to the external force. Derive $F = k m a$ from the second law.</p> <p>The Newton is defined as the force required to produce an acceleration of $1 ms^{-2}$, on a mass of $1 kg$.</p> <p>From Newton's second law of $F = k m a$ using the definition of the Newton show that $k = 1$. Therefore $F = ma$. Hence m is measured in kilograms a in meters per second per second (ms^{-2}) then F is measured in Newtons.</p>	15

Com. Level	Learning Outcomes	Guidelines for Subject Matter	No. of Periods
	<p>11. Explains the vector nature of the equation $\underline{F} = m\underline{a}$ from second law of motion.</p> <p>12. States the gravitational units of force.</p> <p>13. Explains the difference between mass and weight of a body.</p> <p>14. Describes “action” and “reaction”.</p> <p>15. States Newton’s third law of motion.</p> <p>16. Solves problems using $\underline{F} = m\underline{a}$.</p>	<p>According to $\underline{F} = m\underline{a}$ the acceleration takes place in the direction of the force \underline{F}. Show that the equation could be used by resolving the force and the acceleration in any direction.</p> <p>Introduce kg weight as the gravitational force with which a mass of $1kg$ is pulled towards the earth, gravitational attraction.</p> <p>Introduce that the mass of a body is the amount of matter contained in it and that the weight of a body is the gravitational force with which that body is attracted towards the earth. State that when the mass is measured in kg, and the acceleration due to gravity is measured in ms^{-2} the units of weight is obtained in N.</p> <p>Draw the attention of students to different types of forces - using examples show how forces always occur in pairs. For example, action and reaction between two bodies in contact.</p> <p>“For every action between bodies, there is a reaction of equal magnitude and opposite direction along the same line of action”</p> <p>Students are expected to solve problems related to following cases.</p> <ol style="list-style-type: none"> i. Find acceleration of a body under the action of given external forces. Find external force when the acceleration is given. Find reaction between body and a lift when the lift is moving with given acceleration. The acceleration produced by external forces acting on two bodies connected by a string and the tension in the string. ii. When forces act on a system of bodies., find the acceleration of each body of the system and reactions between bodies in the system. iii. Calculate frictional forces acting, by considering the motion of a body on a rough plane. iv. Problems relating to the motion of systems comprising of connected particles or rigid bodies. v. Motion of particle on a smooth wedge, which may (including smooth pulleys) moving on a smooth plane. 	

Com. Level	Learning Outcomes	Guidelines for Subject Matter	No. of Periods
2.8	1. Describes “friction” and “Frictional force”. 2. Distinguishes between smooth and rough surfaces. 3. States the advantages and disadvantages of friction. 4. Describes “Limiting frictional force”. 5. State laws of friction	<p>Introduce frictional force as a force acting along the tangential plane that prevents or tends to prevent relative motion between two bodies in contact. The property that produces this force is called friction. State that as the applied force is gradually increased the frictional force too increases until the equilibrium ceases to exist.</p> <p>From the surfaces under impact, introduce that the surfaces without a frictional force as smooth surfaces and surfaces with a frictional force as rough surfaces.</p> <p>Discuss the advantages and disadvantages of friction using suitable examples.</p> <p>Introduce “Limiting frictional force” as the maximum frictional force between two surfaces at the instant when relative motion between the two surfaces in contact is about to commence.</p> <p>(1) When two bodies on contact undergo motion relative to each other the frictional force exerted by one body on the other is opposite to the direction in which the body moves or tends to move relative to the other.</p> <p>(2) When in equilibrium the frictional force is just sufficient to prevent relative motion.</p> <p>(3) The ratio of the limiting frictional force to the normal reaction at the point of contact is a constant, called the coefficient of limiting friction and depends only on the material the surface of the bodies are made of.</p> <p>(4) As long as the normal reaction remains unchanged, the limiting frictional force does not depend on the area of contact or the shape of the two surfaces.</p> <p>(5) When the motion sets in the limiting frictional force decreases slightly.</p> <p>(6) When there is relative motion between the surfaces, the ratio of the frictional force and the normal reaction is slightly less than the coefficient of limiting friction.</p>	10

Com. Level	Learning Outcomes	Guidelines for Subject Matter	No. of Periods
	<p>6. Defines coefficient of limiting friction.</p> <p>7. Introduces angle of friction.</p> <p>8. Expresses the conditions for equilibrium.</p> <p>9. Solves problems related to equilibrium of a particle or a rigid body, under the action of forces including frictional forces.</p>	<p>Define the coefficient of limiting friction between any two given surface as the ratio of the limiting frictional force to the normal reaction. If F_f is the limiting frictional force and R is normal reaction then $\mu_s = \frac{F_f}{R}$ is called coefficient of limiting friction. This is also called the coefficient of static friction.</p> <p>Introduce the angle of friction as the angle made by the total reaction with the normal reaction when the equilibrium is limiting. If the angle of friction is λ; deduce the result $\mu_s = \tan \lambda$</p>  <p>Show that the frictional force F between two surfaces of contact at any time is given by $F \leq \mu_s \cdot R$. (equality occurring at limiting equilibrium) and hence $F \leq \mu_s R$.</p> <p>Direct students to solve friction related problems.</p>	

Com. Level	Learning Outcomes	Guidelines for Subject Matter	No. of Periods
2.9	<p>1. Describes different types of joints.</p> <p>2. Describes the difference between movable joint and rigid joint.</p> <p>3. Describes smooth hinge (Nut and Bolt joint)</p> <p>4. Solves problems involving smooth joints.</p>	<p style="text-align: center;">Joints</p> <pre> graph TD Joints --> MovableJoints[Movable Joints] Joints --> RigidJoints[Rigid Joints] MovableJoints --> BowlJoints[Bowl Joints] MovableJoints --> SmoothRoughMovable[Smooth Rough] RigidJoints --> Hinges[Hinges (Nut and Bolt Joints)] Hinges --> SmoothRoughRigid[Smooth Rough] </pre> <p>Discuss each type of joint by considering examples in every day life.</p> <p>Introduce that</p> <p>(i) A joint where the position of rods cannot be changed relative to one another as a rigid joint.</p> <p>(ii) A joint where the position of rods can be changed relative to one another as a movable joint.</p> <p>State that the light or heavy rods, considered are joined by smooth hinges (Nut and Bolt joints). Show that since the joint is smooth the force acting at the joint act in the plane of the two rods and that the reactions between the rods under the action of external forces are equal in magnitude and opposite in direction.</p>  <p>Direct students to solve relevant problems.</p>	10

Com. Level	Learning Outcomes	Guidelines for Subject Matter	No. of Periods
2.10	<p>5. Solves problems dealing with rigid joints.</p> <p>1. Introduces a frame work with light rods.</p> <p>2. States the assumptions made in considering frame works.</p> <p>3. States the conditions necessary for the equilibrium of each joint.</p> <p>4. When the frame work is symmetrical marks the external forces acting on it.</p> <p>5. States Bow's notation.</p>	<p>Emphasize that the equilibrium cannot be considered as that of two bodies by disjoining the joint. Show that solving problems involving two rods jointed rigidly has to be considered as single rigid body. (Rough hinges are not within the syllabus)</p> <p>Introduce a fram work as a structure consisting of three or more straight light rods hinged at their ends such that they are in the same plane. Describe using suitable examples.</p> <p>(i) All the rods are smoothly joined at their ends so that no couple or torque is produced.</p> <p>(ii) Except for the external forces, all the reactions at the joints act along the rods. These can be either tensions or thrusts.</p> <p>(iii) All the rods lie in the same vertical plane. Therefore all the forces in the system including external forces are coplanar.</p> <p>(i) As the entire frame work is in equilibrium, all the external forces should be in equilibrium.</p> <p>(ii) As each joint is in equilibrium under the action of forces acting on it (external forces and the stress meeting in the joint) the principle of polygon of forces can be applied to each joint.</p> <p>Show using suitable examples how the symmetrical property of the system is used in marking the forces and how to use conditions of equilibrium in finding them.</p> <p>Tell the students that, as this method was found by a Mathematician by the name of "Bow" the method is called "Bow's notation".</p>	

Com. Level	Learning Outcomes	Guidelines for Subject Matter	No. of Periods
	<p>6. Draws the stress diagram for the frame work.</p> <p>7. Calculates the stresses by the method of Bow's notation.</p>	<p>Method:-</p> <p>(i) Mark the external forces acting on a frame work, outside this frame work itself.</p> <p>(ii) Number all areas bounded by every pair of external forces and rods.</p> <p>(i) Draw a triangle of forces, or a polygon of forces representing forces at a joint, with one or two unknown forces. (these force diagram should be a closed polygon).</p> <p>(ii) Draw triangles or polygons of forces for adjoining joints taken in order. These figures too should be closed.</p> <p>(i) Find unknown stresses by considering the triangles or polygons in the stress diagram, and using trigonometric or algebraic formulae.</p> <p>(ii) Show that (if necessary) unknown external forces can also be determined, using the stress diagram.</p> <ul style="list-style-type: none"> ● Draw the attention of students to avoid using arrow heads on the stress diagram, but use these on the frame work diagram. ● Explain how the stress could be classified as tensions and thrust according to the arrow heads inserted on the frame work diagram. 	

Combined Maths

Grade 12

Teacher's Instruction Manual

School Based Assessment

Introduction- School Based Assessment

Learning -Teaching and Evaluation are three major components of the process of Education. It is a fact that teachers should know that evaluation is used to assess the progress of learning-teaching process. Moreover, teachers should know that these components influence mutually and develop each other. According to formative assessment (continuous assessment) fundamentals; it should be done while teaching or it is an ongoing process. Formative assessment can be done at the beginning, in the middle, at the end and at any instance of the learning teaching process.

Teachers who expect to assess the progress of learning of the students should use an organized plan. School based assessment (SBA) process is not a mere examination method or a testing method. This programme is known as the method of intervening to develop learning in students and teaching of teachers. Furthermore, this process can be used to maximize the student's capacities by identifying their strengths and weaknesses closely.

When implementing SBA programmes, students are directed to exploratory process through Learning Teaching activities and it is expected that teachers should be with the students facilitating, directing and observing the task they are engaged in.

At this juncture students should be assessed continuously and the teacher should confirm whether the skills of the students get developed up to expected level by assessing continuously. Learning teaching process should not only provide proper experiences to the students but also check whether the students have acquired them properly. For this, to happen proper guiding should be given.

Teachers who are engaged in evaluation (assessment) would be able to supply guidance in two ways. They are commonly known as feed-back and feed- forward. Teacher's role should be providing Feedback to avoid learning difficulties when the students' weaknesses and inabilities are revealed and provide feed-forward when the abilities and the strengths are identified, to develop such strong skills of the students.

Student should be able to identify what objectives have achieved to which level, leads to Success of the Learning Teaching process. Teachers are expected to judge the competency levels students have reached through evaluation and they should communicate information about student progress to parents and other relevant sectors. The best method that can be used to assess is the SBA that provides the opportunity to assess student continuously.

Teachers who have got the above objective in mind will use effective learning, Teaching, evaluation methods to make the Teaching process and learning process effective. Following are the types of evaluation tools student and, teachers can use. These types were introduced to teachers by the Department of Examination and National Institute of Education with the new reforms. Therefore, we expect that the teachers in the system know about them well

Types of assessment tools:

1. Assignments
2. Projects
3. Survey
4. Exploration
5. Observation
6. Exhibitions
7. Field trips
8. Short written
9. Structured essays
10. Open book test

- | | |
|------------------------------|--------------------------|
| 11. Creative activities | 12. Listening Tests |
| 13. Practical work | 14. Speech |
| 15. Self creation | 16. Group work |
| 17. Concept maps | 18. Double entry journal |
| 19. Wall papers | 20. Quizzes |
| 21. Question and answer book | 22. Debates |
| 23. Panel discussions | 24. Seminars |
| 25. Impromptus speeches | 26. Role-plays |

Teachers are not expected to use above mentioned activities for all the units and for all the subjects. Teachers should be able to pick and choose the suitable type for the relevant units and for the relevant subjects to assess the progress of the students appropriately. The types of assessment tools are mentioned in Teacher's Instructional Manuals.

If the teachers try to avoid administering the relevant assessment tools in their classes there will be lapses in exhibiting the growth of academic abilities, affective factors and psycho- motor skills in the students

Grade 12 First Term - Evaluation Plan - 1
(Combined Maths - I)

01. Competency : 15. Derives relations involving measurement of angles to solve problems.
Competency Level : 15. Derives relations involving measurement of angles to solve problems.

02. Nature of Evaluation Plan : Group activity of finding the length of an arc of a circle and the area of a sector.

03. Time : 100 minutes

04. Instructions for the implementation of the evaluation plan :

- Prepare
- (1) Copies of work sheets in annexure 1
 - (2) Protractor
 - (3) Thread
 - (4) Pins
 - (5) Ruler

Step 1 :

- (i) Divide the students into two groups A and B.
- (ii) Provide the group with copies of worksheet (1).
- (iii) Direct the students to present the explanation to the class.
- (iv) Prepare the students to present the explanation to the class.

Step 2 :

- (i) Divide the students into two groups A and B.
- (ii) Provide the group with copies of worksheet (2).
- (iii) Direct the students to engage in the activities as instructed.
- (iv) Prepare the students to present the explanations to the class.

05. Criteria for Evaluation :

1. Expressing the arc length and the area of the sector subtended by it in terms of the radius and the radians in the angle it subtends at the centre.
2. Realises that the arc length and the area of the sector can be determined when the radius r of the circle and the angle subtends at the centre are known.
3. Calculating arc length and the area of the sector when the radius of the circle and the angle subtended at the centre are given.
4. Inclination for the exploration of suitable mathematical models required for calculations arising in day to day life.
5. Selecting suitable solutions in solving problems.

Work Sheet (1)

- Your group is required to engage in the activity according to the instructions given. Be prepared to present the explanations to the class at the end of the activity.

Group A

- Draw the line OA 5cm long.
- With centre as O, draw 4 circles with radius 2cm, 3cm, 4cm and 5cm.
- Mark the points of intersection of the circles with the line OA as P, Q and R.
- Taking a piece of thread marked 2cm on it mark points 2cm from P on the circumference of the circle with radius 2cm: mark those points as P_1 .
- Mark the points of intersection of other circles when OP_1 is produced as Q_1 and R_1 .
- Measure the lengths of the arcs QQ_1 and RR_1 .
- Measure the angle QOR_1 .
- What can you say about the angle subtended by an arc of any circle equal to its radius?

Group B

- Draw a line segment OA, 4cm long and draw a circle with radius OA.
- Taking a piece of thread marked 4cm on it mark the point P, 4cm from A on the circumference. Join that point to O. Measure the angle obtained.
- Mark two angles equal to \widehat{POA} away from OA and OP.
- If Q and R are the points where the sides of those angles meet the circle measure the arcs AQ and PR.
- What can you say about the arc lengths when the angles subtended at the centre of a circle are equal?

Work Sheet (2)

- Your group is required to engage in the activity according to the given instructions. Be prepared to present explanations to the class at the end of the activity.
- Group A should complete the tables (1) and (2) and Group B should complete tables (1) and (3). Answer the given questions using the tables.

Table (1)

Radius of Circle	Angle subtended at the centre	Length of the arc subtending that angle
r	1 Radian
r	3 Radians
.....	5 Radians
2 Radians
r	θ Radians

Table (1)

Radius of Circle	Angle subtended at the centre	Length of the arc subtending that angle
.....	1 Radian	r
.....	θ Radians	$r \theta$
r Radians	$2\pi r$
r Degrees	$2\pi r$
4	60 Degrees

Table (3)

Radius of Circle	Angle subtended at the centre	Area of a sector of a circle subtending that angle
.....	360°	πr^2
r	2π	$\frac{1}{2}(\text{.....})r^2$
.....	π
.....	θ
.....	$\frac{\pi}{3}$

- Denote a relation between degrees and radians.
- Write P in radians.
- Write the value of a radian in degrees.

Grade 12 First Term - Evaluation Plan - 2
(Combined Maths - I)

01. Competency : 18. Applies sine formula and cosine formula to solve trigonometric problems.

Competency Level : 18. Applies sine formula and cosine formula to solve trigonometric problems.

02. Nature of Evaluation Plan :

It is an assignment which can be implemented for the main groups under the theme sine rule and cosine rule.

It is expected to obtain a knowledge about the relationship between the length of the sides and trigonometric ratios in triangular figures of various shapes.

The final outcome will be a table consisting practical values denoting that relation.

03. Time : 90 minutes

04. Instructions for the implementation of the evaluation plan :

(a) Pre-requisites and instructions.

(i) Provide the students with the previous knowledge required to implement the assignment. Discuss with students about practical situations involving the finding of lengths of sides of a triangle.

(ii) Divide the students into groups.

(iii) Prepare work sheets required for the groups. When there are several groups provide them with parallel work sheets.

(iv) Make the students aware of the materials required for the task assigned to each group and the evaluation criteria.

(v) Prepare materials for the two groups as follows.

A white A₄ paper, pencil, eraser, two pieces of white thread, a meter scale, a protractor, a wooden board to fix the white paper, drawing pins, two nails about 3cm long.

(b) Procedure

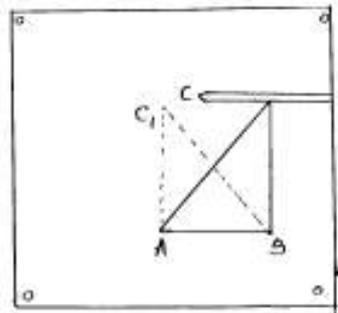
(i) Providing each group with a work sheet and engage them in the activity.

(ii) Watch the groups and give instructions and guidance to make the assignment a success.

Work Sheet for Group 1

You are required to measure sides of various triangles with sides of different length and to test that they agree with the sine rule and the cosine rule.

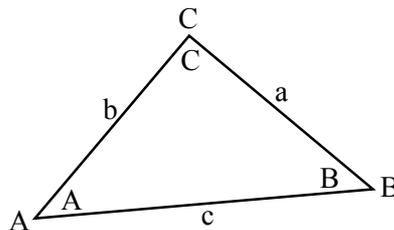
- (i) Read this work sheet and discuss among you how to accomplish the task assigned to you.
- (ii) Fix the A4 paper to the wooden board with pins



- (iii) On the lower end of the paper draw a line AB of sufficient length parallel to the lower edge. Measure the length of AB. Fix firmly the two nails on the vertices A and B. Tie two unequal pieces of thread to A and B. Join the free ends of the threads to a pencil. If C is the pencil point take the length of BC less than AB. AC and BC are the two pieces of thread and C is the pencil point.
- (iv) Initially place the pencil point on the paper with the thread BC perpendicular to AB and with the threads taut and mark the point C_1 . Similarly changing the length of AB mark at least 5 positions for C with the threads taut, on the plane of the paper rotating the point C anticlockwise. Takes cases for $\angle C \hat{A} B < \frac{\pi}{2}$ only. Measure AC and BC. (obtain the length of BC varying the length AC).

- (v) Trace the edges AC and CB for various positions of C and measure $\angle C \hat{A} B$ and $\angle C \hat{B} A$ for each position.

- (vi)



Complete the following table taking $\angle C \hat{A} B = \hat{A}$, $\angle C \hat{B} A = \hat{B}$, $AC = b$ and $CB = a$, $AB = c$.

- (vii) $\hat{A} + \hat{B} + \hat{C} = 180^\circ$

Table 1

AC b	BC a	$\frac{a}{\sin \hat{A}}$	$\frac{b}{\sin \hat{B}}$	$\frac{c}{\sin \hat{C}}$	$\cos \hat{A}$	$\frac{b^2 + c^2 - a^2}{2bc}$

(viii) Give your conclusions about the ratios

$$\frac{a}{\sin A}, \frac{b}{\sin B}, \frac{c}{\sin C}.$$

(ix) What is your conclusion about $\cos A$ and $\frac{b^2 + c^2 - a^2}{2bc}$.

Work Sheet for Group 2

Work sheet will be the same as for Group 1, but take the magnitudes of sides and angles for

$$\angle C \hat{A} B > \frac{\pi}{2}.$$

05. Criteria for Evaluation :

1. It is expected to evaluate the preparation, the finish of the procedure and the traits of the students with regard to the assignment.
2. Group mark or personal marks may be given for the criteria in the evaluation model.
3. Assign marks for each criterion as follows,
Excellent - 4 Very good - 3
Good - 2 Average - 1
4. Accordingly the maximum number of marks entitled to a student is $14 \times 4 = 56$.

Evaluation Model

(01) Preparation

- (i) Taking part in the discussion brilliantly.
- (ii) Exchange of ideas with the teacher.
- (iii) Exchange of ideas with other students.
- (iv) Contribution towards planning the activities.

(02) Engaging in the process

- (i) Selecting lengths AB, AC, BC suitably.
- (ii) Selecting lengths AB and BC suitably.
- (iii) Measuring triangles

(03) Finish

- (i) Preparation of the table
- (ii) Conclusion about ratios .
- (iii) Conclusion about and .

(04) Traits exhibited in the student from the beginning to the end of the assignment.

- (i) Obeying teacher instructions.
- (ii) Interest in taking measurements.
- (iii) Co-operation with the group.
- (iv) Ability to tolerate opinions of others.

Grade 12 First Term - Evaluation Plan - 3
(Combined Maths - II)

01. Competency : 1. Manipulates Vector Algebra.
Competency Level : 1.3 Applies position vector as a technique of solving problems.

02. Nature of Evaluation Plan : Solving problems using position vectors is a group activity.

03. Time : 90 minutes

04. Instructions for the implementation of the evaluation plan :

Get supplies with following materials.

- (i) Three copies of the work sheet in annexure 1.
- (ii) Demi papers
- (iii) Marker pens

Step 1 :

- (i) Divide the students into three groups A, B and C.
- (ii) Prepare the students to present the explanations to the class.

05. Criteria for Evaluation :

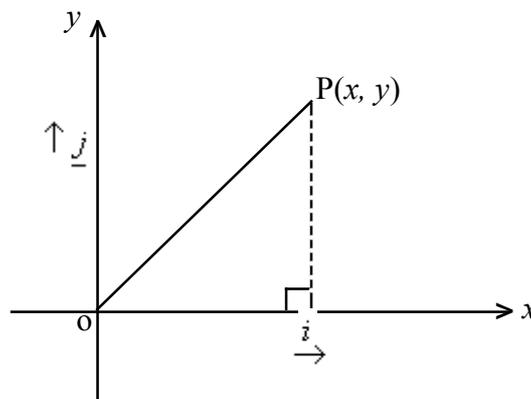
- 1. Expressing what the position vector of a point is.
- 2. Realising that by using position vectors, the position of any point in relation to a given point can be determined distinctly.
- 3. Applying the information studied to solve problems.
- 4. Communication of information using various techniques.
- 5. Using previous experience to obtain new experience.

Work Sheet

- Get engaged in the task assigned to your group.
- Be prepared to present group explanations to the whole class.

For all groups

The unit vector along the x -axis is \underline{i} and the unit vector along the y -axis is \underline{j} . The position of a point $P(x, y)$ in relation to a system of axes ox, oy is denoted in the following diagram.



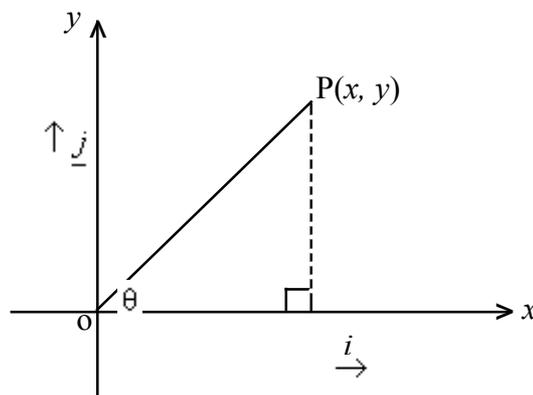
Obtain that $\overrightarrow{OP} = x\underline{i} + y\underline{j}$

For Group A

- Consider that the position vector of A is $\overrightarrow{OA} = \underline{a}$ and the position vector B is $\overrightarrow{OB} = \underline{b}$ in relation to a point O. Denote these data in a diagram. Obtain an expression in \underline{a} and \underline{b} for \overrightarrow{AB} .
- Deduce an expression for \overrightarrow{BA} .

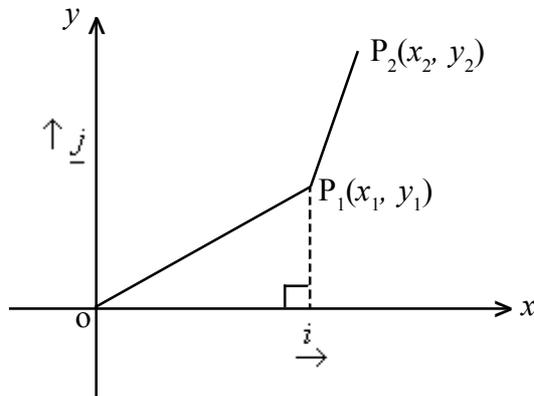
For Group B

- Consider the point $P(x, y)$.



- (i) Express \overrightarrow{OD} , \overrightarrow{DP} and \overrightarrow{OP} in terms of \underline{i} and \underline{j} .
- (ii) Express the unit vector along the vector \overrightarrow{OP} (\underline{u}) in terms of \underline{i} , \underline{j} and θ only.

For Group C



- (i) Express the position vectors of the points P_1 and P_2 denoted in the diagram in terms of the unit vectors \underline{i} and \underline{j} and the co-ordinates of those points.
- (ii) Hence find $\overrightarrow{P_1P_2}$.
- (iii) Express the unit vector along $\overrightarrow{P_1P_2}$.

Grade 12 Second Term - Evaluation Plan - 1
(Combined Maths - I)

- 01. Competency** : 3. Analyses Quadratic Functions.
Competency Level : 3.1 Investigates the properties of a quadratic function.
- 02. Nature of Evaluation Plan** : It is a group activity of finding the properties of a quadratic function.
- 03. Time** : 120 minutes

04. Instructions for the implementation of the evaluation plan :

Get supplied with

- (i) Six copies of the instructions sheet in annexure 1
- (ii) A bristol board prepared according to the note in annexure 2.
- (iii) Demi papers
- (iv) Marker pens

- Step 1** : (i) Divide the class into six groups.
(ii) Supply each group with a copy of the worksheet.
(iii) Get the groups engaged as instructed in the work sheet.
(iv) Prepare the groups to present their explanation to the class.

05. Criteria for Evaluation :

1. Describing the properties of the quadratic function.
2. Realises that the shape of a quadratic function can be determined by the properties of a and Δ .
3. Determining the behaviour of a quadratic function by considering the coefficient of the square term and its discriminant.
4. Activity with co-operation with in the group.
5. Derivation of more efficient methods for prediction.

Work Sheet

- You are required to choose the quadratic function relevant to your group from the following functions.

Group A - $f(x) = 2x^2 - 4x + 5$

Group B - $f(x) = -3x^2 + 2x - 1$

Group C - $f(x) = x^2 - 3x + 2$

Group D - $f(x) = -2x^2 + 3x + 5$

Group E - $f(x) = x^2 - 2x + 1$

Group F - $f(x) = -x^2 + 2x - 1$

- Do the following activity according to the given instructions.

- (i) For the given function $y = f(x)$ complete the following table.

x	-3	-2	-1	0	1	2	3	4
y								

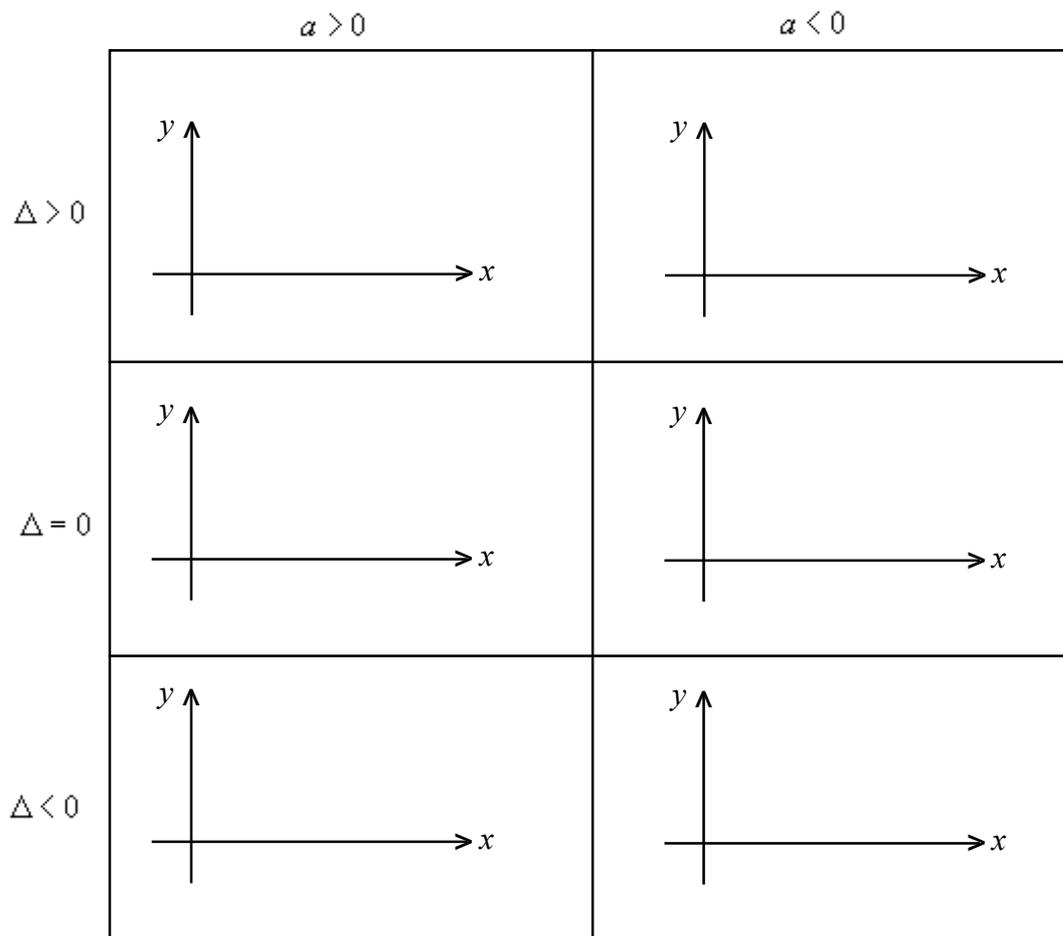
- (ii) Draw the graph of $y = f(x)$ for the interval $-3 \leq x \leq 4$.

- (iii) Using the graph drawn answer the following questions.

- What is the greatest or the least value of the function?
- Write the equation of the symmetrical axis of the graph.
- Write the co-ordinates of the vertex of the graph.
- Are there points where the y co-ordinate is zero? If so, write their x co-ordinates.
- By completing the square write the given function in the form $f(x) = A(x + B)^2 + C$;
 $A, B, C \in \mathbb{R}$.
- Using the result obtained in (e) answer the questions (a), (b), (c) and (d) above.
- When the given function is compared with the standard form $f(x) = ax^2 + bx + c$.
What is the sign of a ?
- $b^2 - 4ac$ in the general quadratic function is called the discriminant. It is generally denoted by Δ (delta). Write the value of Δ for the given function.
- What is the sign of Δ ?

- Mark the graph drawn at the appropriate place of the poster hung in the class.

Model for making the explanations (Graphs)



Grade 12 Second Term - Evaluation Plan - 2

(Combined Maths - II)

01. Competency : 3. Perceives natural motions on a plane using the Newtonians model for motion

Competency Level : 3.1 Use graphs to solve problems involving the motion on a straight line.

02. Nature of Evaluation Plan :

- (i) It is a group activity which can be implemented under the theme of motion along a straight line.
- (ii) Can realise the difference between displacement and distance, average velocity and average speed.
- (iii) Find outcome will be a table of numerical values obtained for average speed and average velocity and a wall newspaper with displacement - time and distance - time graphs.

03. Time : 90 minutes

04. Instructions for the implementation of the evaluation plan :

- (a) Prerequisites and Instructions.
 - (i) On a day before implementing the assignment discuss with the students about practical situations and their aims.
 - (ii) Prepare work sheets required for the groups.
 - (iii) Make groups with 5 to 6 students. When there are several groups give parallel work sheets.
 - (iv) Create an awareness among students about the materials and information that have to be supplied according to the task assigned to each group and the evaluation criteria.
 - (v) Prepare materials for each group as follows.

Materials and information for group 1

Piece of chalk, meter scale, four stop watches, rubber ball or a piece of wood.

Materials and information for group 1

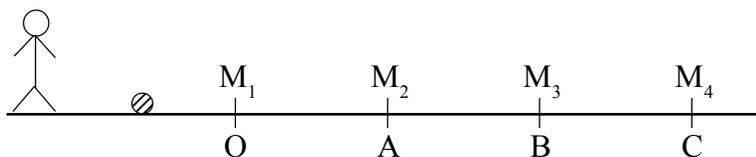
Piece of chalk, meter scale, five stop watches, rubber ball, a plank that can be used as a barrier.

(even a wall is suitable for this purpose)

- (b) Procedure
 - (i) Engage each group in the activity by providing them with relevant work sheets.
 - (ii) Watch the groups in activity and give them necessary instructions for its success.
 - (iii) Give opportunity to present their creations to the class.

Work Sheet for Group 1

- Your group is required to measure the displacement and distance of a particle moving on a straight line and to calculate the average speeds and velocities in the given time intervals. This can be accomplished by projecting a ball or an object through four points in the cemented floor of your school compound and measuring the time taken to pass each point.
 - (i) Discuss the task assigned with the members in the groups.
 - (ii) Provide a ball, meter scale, four stop watches and 2 graph papers for each member.
 - (iii) Mark 4 points on the cemented floor in the school compound from 3m-4m apart by the piece of chalk. Name these points as O, A, B and C. The distances between them need not be equal.



- (iv) Place four students M₁, M₂, M₃ and M₄ with stop watches in front of the points O, A, B and C.
- (v) From a sufficient distance from O project the rubber ball along the floor with a suitable velocity to pass through the 4 points.
- (vi) At the moment the ball is projected all students should activate their stop watches.
- (vii) As the ball reaches each point the student beside that point should stop the watch and obtain the relevant reading.
- (viii) Measure the distance from O to A, B and C.
- (ix) Tabulate your readings as follows.

Displacement	time taken for the journey
OA =	t _{OA} = time taken to travel from O to A
OB =	t _{OB} =
OC =	t _{OC} =

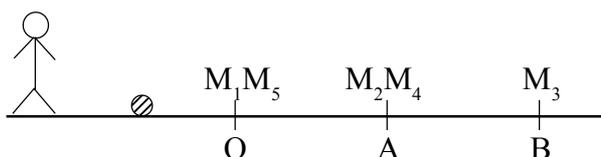
- (x) Draw the *s-t* graph.
- (xi) Use, Average velocity = $\frac{\text{Difference in displacement}}{\text{Difference in time}}$
 and average speed = $\frac{\text{Difference in distance}}{\text{Difference in time}}$
 to complete the following table.

Intervals	Average velocity	Average speed
OA		
OB		
OC		
AB		
BC		

- (xii) Discuss your results and conclusions with other groups.

Work Sheet for Group 2

- Your group is required to measure the displacements and distances between some points taken on a straight line and to calculate the average velocity and average speed of a body passing through the points. You are required to measure the displacements and distances between several selected points and measure the time taken to make those displacements by a ball passing through them.
 - Discuss the task assigned to you with other members in the groups.
 - Obtain a ball, meter scale to measure displacement and distance, 5 stop watches to measure time, a piece of chalk, a plank or a similar object which can be used as a barrier and two graph papers for each member in the group.
 - Mark three points O, A and B about 3m - 4m apart on the cement floor in the school compound using the piece of chalk. Their distances may not be equal. Place the barrier at B perpendicular to OAB. (A wall may be used as the barrier)



- Place five students with stop watches as follows.
 - Two students M_1 and M_5 with stop watches.
 - Two students M_2 and M_4 at A.
 - One student M_3 at B.
- Project the ball along the ground from a sufficient distance from O with a suitable velocity to pass through O, A and B and after hitting the barrier at B to reach O or pass through O.
- Immediately after projecting the ball all students should activate their stopwatches.
- When the ball travels through O, A and B, M_1 , M_2 and M_3 should stop their stopwatches, when B reaches A and O after hitting B, M_4 and M_5 should stop their stopwatches.
- Obtain the readings of the stopwatches.
- Measure distances from O to A and B.

- (x) Tabulate the values obtained as follows.
- (xi) From the values obtained above draw a displacement-time curve and a distance - time curve.

	Displacement	Distance	Time
Journey OA			
„ OB			
„ OBA			
„ OBAO			

05. Criteria for Evaluation :

1. It is expected to evaluate the readiness, finish and the traits of students towards the activity. Use the model given for it.
2. Assign marks for the criteria in the evaluation model group - wise or individual student - wise as circumstances demand. Group marks will be the individual mark of the student for each criterion.
3. Assign marks for each criterion as follows.
 Excellent - 4 Very good - 3
 Good - 2 Average - 1
4. Accordingly the maximum mark a student entitled to is $12 \times 4 = 48$.

Evaluation Model

Criteria	Name of Student	
	Group 1	Group 2
<p>(01) Preparedness</p> <ul style="list-style-type: none"> (i) Energetic participation in discussion. (ii) Exchange of ideas with the teacher. (iii) Exchange of ideas with other students. (iv) Contribution towards planning the activities. <p>(02) Engaging in the activity</p> <ul style="list-style-type: none"> (i) Selecting O, A, B, C suitably. (ii) Throwing the ball appropriately. (iii) Measuring time. (iv) Measuring displacement. <p>(03) Finish</p> <ul style="list-style-type: none"> (i) Preparing table 1. <p>(04) Traits exhibited by the student from the beginning to the end of the activity.</p> <ul style="list-style-type: none"> (i) Following teacher instructions. (ii) Interest shown in taking measurements. (iii) Co-operation with the group. 		

Grade 12 Second Term - Evaluation Plan - 3
(Combined Maths - II)

01. Competency : 3. Perceives natural motions taking place on a plane using the Newtonian model for motion.

Competency Level : 3.1 Uses kinetic equations to solve problems on motions along a straight line.

02. Nature of Evaluation Plan : It is a group activity of constructing equations for motion.

03. Time : 80 minutes

04. Instructions for the implementation of the evaluation plan :

1. Four copies of the work sheet in annexure 1.
2. Demi papers.
3. Marker pens, should be supplied.

Step 1 :

- (i) Divide the class into 4 small groups.
- (ii) Provide each group with a copy of the work sheet.
- (iii) Distribute demi papers, marker pens and copies of the work sheet among groups.
- (iv) Get the groups engaged in the activities.
- (v) Prepare the students to present explanations to the class.

05. Criteria for Evaluation :

1. Construction of kinetic equations on motion.
2. Realising that application of kinetic equations is convenient in solving some problems.
3. Solving problems using kinetic equations.
4. Exploring alternate methods for solving problems.
5. Facilitating the task by constructing models.

Work Sheet

- You are required to engage in the activity according to given instructions.
- Select the process relevant to your group. Hence construct the following equations.

$$(i) \quad v = u + at$$

$$(ii) \quad s = ut + \frac{1}{2}at^2$$

$$(iii) \quad v^2 = u^2 + 2as$$

Group A

Use the relations $\underline{a} = \frac{v - u}{t}$ and $s = \frac{(u + v)}{2}t$

Group B

If the initial velocity is \underline{u} , acceleration is \underline{a} , final velocity is \underline{v} , time is t and displacement is s m construct a velocity - time curve. Use the gradient and the area between the curve and the time axis.

Group C

When in vertical motion under constant gravitational acceleration g use the relations $\underline{a} = \frac{v - u}{t}$

and $s = \frac{(u + v)}{2}t$.

Group D

When in vertical motion constant gravitational acceleration g , its initial velocity is \underline{u} , acceleration is \underline{g} , final velocity is \underline{v} , time is t and displacement is s , construct a velocity-time curve. Use gradient and the area between the curve and the time axis.

Question

Group A and B	If is $\underline{a} = -2ms^{-2}$, $\underline{v} = 5ms^{-1}$, $t = 3s$ then find \underline{u} and \underline{s}
Group C and D	If is $\underline{s} = 490m$, $t = 10s$, $\underline{v} = 98ms^{-1}$ then find \underline{u} and \underline{a}

Grade 12 Third Term - Evaluation Plan - 1
(Combined Maths - II)

- 01. Competency** : 3. Perceives natural motions taken place on a plane using the Newtonians model for motion.
Competency Level : 3.5 Determines the motion of a particle on a plane relative to another particle.

- 02. Nature of Evaluation Plan** : It is a group activity of inquiring into the relativity of motion.

- 03. Time** : 90 minutes

04. Instructions for the implementation of the evaluation plan :

1. Three copies of the work sheet in annexure 1.
2. Demi papers, Marker pens should be supplied.

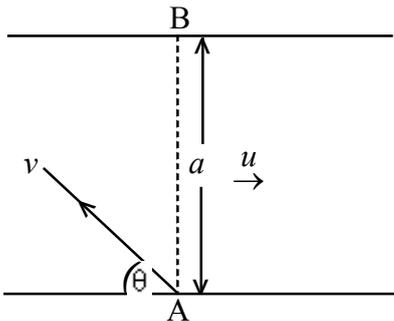
- Step 1** :
- (i) Divide the class into three groups A, B and C.
 - (ii) Provide each group with a copy of work sheet.
 - (iii) Supply demi papers and marker pens to the groups.
 - (iv) Engage the groups in the task.
 - (v) Prepare the groups to present explanations to the class.

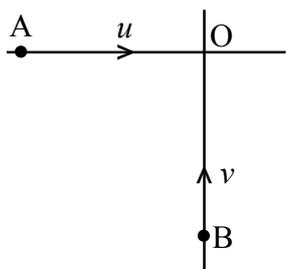
05. Criteria for Evaluation :

1. Expresses the principles of relative motion describing the motion of one particle relative to each particle on a plane.
2. Appreciates the applicability of the principles of relative motion in studying a motion.
3. Applies the principles of relative motion in solving problems on motion.
4. Applies theoretical models for solving practical problems.
5. Look at some events objectively from all angles.

Work Sheet

- Three events relating to relative motion are given below. You are required to select the event relevant to your group and study it under the following topics.
 - Event
 - Problem
 - Information leading to the solution of the problem.
 - Solution
 - Assumptions made
 - Practical importance
- Make use of the guidelines provided in studying the problem.

Group	Event
A	<div style="display: flex; align-items: center;">  <div style="margin-left: 20px;"> <p>A river of width a with parallel banks is following with a velocity u.</p> <p>A and B are two ferries on the opposite banks. Where $AB = a$. A ferryman rows his boat with a velocity v intending to reach B from A. Assume that he is rowing the boat pointed at an angle θ with the upward direction of the river.</p> <p>Discuss the situations</p> <p>(i) $u > v \cos \theta$</p> <p>(ii) $u = v \cos \theta$</p> </div> </div>
B	<p>On a day when the wind is blowing steadily, for a cyclist travelling north with a velocity v, the wind appears to be flowing from east.</p> <p>(i) Inquire whether the data given above is sufficient to determine the true velocity of the wind and if not state the additional data required.</p> <p>(ii) Stating the factors affecting the apparent direction of the wind discuss whether those factors should act collectively or otherwise in order to change the apparent direction.</p>

C	<div style="display: flex; justify-content: space-between; align-items: center;"> <div style="text-align: center;">  </div> <div style="width: 45%;"> <p>Two perpendicular linear highways intersect at O. In these highways a motor car A is travelling with a velocity u on one way and another motor car B is travelling with velocity v on the other way towards O.</p> </div> </div> <p style="margin-top: 20px;">Let $AO = d_1$; $BO = d_2$ at the time t.</p> <p>Discuss the conditions necessary to avoid a mishap.</p> <ol style="list-style-type: none"> (i) In terms of the principles of relative motion. (ii) by any other method.
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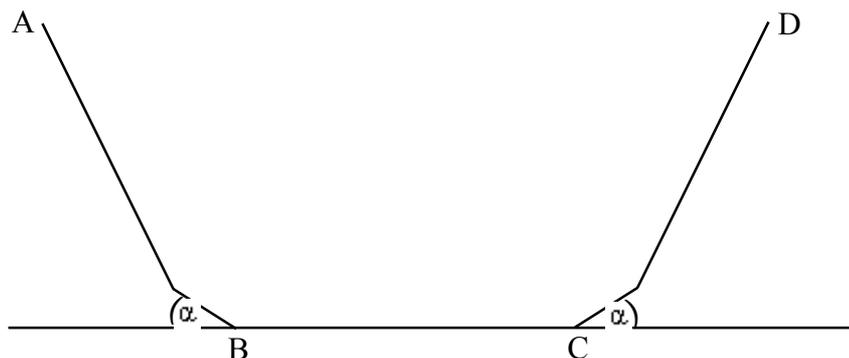
- Be prepared to present your explanations to the class.

Grade 12 Third Term - Evaluation Plan - 2 (Combined Maths - II)

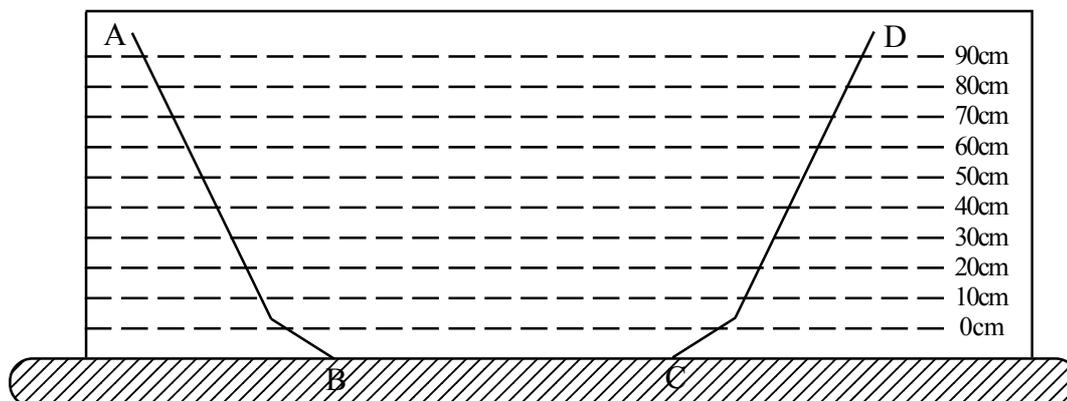
- 01. Competency** : 3. Perceives natural motions taking place on a plane using the Newtonian model on motion.
Competency Level : 3.5 Applies vector methods to solve problems on relative motion.
- 02. Nature of Evaluation Plan** : It is a group activity about simple impact of smooth elastic spheres.
- 03. Time** : 90 minutes
- 04. Instructions for the implementation of the evaluation plan :**

It is a group activity that can be implemented under the theme simple impacts of smooth elastic spheres. The final outcome will be a wall newspaper denoting the ratios of approaching and departing velocities and the momentums before and after impact.

- (a) Prerequisites and instructions.
- (i) On a day before implementing the activity discuss with the students practical situations where impact of elastic spheres occur and their aims. Give them a knowledge of conservation of momentum, approaching and departing relative velocities.
 - (ii) Group the students with about 5 in each group.
 - (iii) Prepare sufficient work sheets for the groups when there are several groups use parallel work sheets.
 - (iv) Create an awareness among the students about the material and information to be supplied for the task and the criteria for evaluation.
 - (v) Make them aware how a motion of a ball takes place in a groove and how the motion accures after the impact.
 - (vi) Take a grooved aluminium hood used for hanging curtains and bend it symmetrically. B and C should take the form of a curve.



Then fix it to a vertical board by means of clips supplied with it with BC horizontal and the plane of the rod vertical. Then graduate in *cm* the vertical height from the level BC on the board.



- (vii) Obtain small plastic balls, glass balls, iron balls, ball bearings of various radii. These balls should be able to move freely in the groove H.
- (viii) Prepare materials for each groups as follows.

Group 1

A board as above, three spheres of same radius and mass, a spring balance suitable for measuring the masses of the spheres.

Group 2

A board as above, two spheres of same radius and different masses, a spring balance suitable to measure the masses of spheres.

Group 3

A board as above, two spheres of different radii and masses, a spring balance to measure the masses of the spheres.

Procedure

- (i) Supply each group with work sheets and engage them in the activity.
- (ii) Watch their activity and give them the necessary instructions and guidelines.
- (iii) At the end of the activity give them an opportunity to discuss among the groups their findings.

Work Sheet for Group 1

- Let them place the two balls supplied on the arms AB and DC at the same or different heights and release them freely so as to cause them to collide in the part BC. Your group is required to observe the way of motion after the impact.
 - (1) Read and understand this work sheet and discuss about the task with the other members in the group.
 - (2) Obtain the materials supplied.
 - (3) Name the two spheres as P and Q and measure their masses.
 - (4) Place on arms AB and DC spheres P and Q at the same or different heights and release them freely so that they collide on BC. Measure the heights h_1 and h_2 . Repeat by changing the heights h_1 and h_2 .
 - (5) After the impact of P and Q on BC try to obtain the following situations of motion.
 - (i) After the impact both spheres move together in the same direction.
 - (ii) After impact they move separately in the same direction.
 - (iii) After impact they move separately in opposite directions.
 - (6) After the impacts (i), (ii) and (iii), obtain the heights h_1 and h_2 the spheres P and Q ascended along the arms BA and CD.
 - (7) Repeat this process several times.
 - (8) Taking $v_2 = \sqrt{2gh}$ calculate the velocity corresponding to the height h and tabulate as shown below.
Calculate the velocities v_1, v_2, v_3 and v_4 corresponding to the heights h_1, h_2, h_3 and h_4 respectively.
Complete the following table.

Table I

	h_1	h_2	v_1	v_2	h_3	h_4	v_3	v_4			$\frac{v}{u}$
1											
2											
3											
4											
...											
...											
...											
...											

- (9) State your conclusion as to the value of $\frac{v}{u}$.
- (10) Since the masses of P and Q are known complete the Table II below.

Table II

	Before impact		After impact		Momentum of system before impact	Momentum of system after impact
	Momentum of P	Momentum of Q	Momentum of P	Momentum of Q		
1						
2						
3						
4						
5						
...						

What is your conclusion about the momentums before and after impact from the table alone?

Work Sheet for Group 2

Same work sheet as for group 1 is used. But the two spheres are of same radius and different masses.

Work Sheet for Group 3

Same work sheet. Spheres are of different radii and masses.

05. Criteria for Evaluation :

1. Readiness, process and traits relevant to the assignment are expected to be evaluated.
2. Marks for the criteria in the evaluation model may be assigned groupwise or personally. The group mark for a criterion will be the personal mark of each student for that criterion.
3. Assign mark for criteria as follows.
Excellent - 4 Very good - 3
Good - 2 Average - 1
Maximum mark entitled for a student is $16 \times 4 = 64$

Evaluation Model

Criteria	Student Names		
	Group 1	Group 2	Group 3
<p>(01) Readiness</p> <ul style="list-style-type: none"> (i) Energetic participation in discussion. (ii) Exchange of ideas with the teacher. (iii) Exchange of ideas with other students. (iv) Contribution towards planning of activity. 			
<p>(02) Engaging in the process</p> <ul style="list-style-type: none"> (i) Measuring masses of spheres. (ii) Choosing h_1 and h_2 suitably. (iii) Measuring time. (iv) Measuring h_1, h_2, h_3 and h_4. 			
<p>(03) Finish</p> <ul style="list-style-type: none"> (i) Calculating v_1, v_2, v_3, v_4 (ii) Completing Table I (iii) Completing Table II (iv) Conclusion about $\frac{v}{u}$ (v) Conclusion on momentums before and after impact. 			
<p>(04) Traits exhibited by the student from the beginning to the end of the assignment.</p> <ul style="list-style-type: none"> (i) Following teacher instructions. (ii) Interest shown in taking measurements. (iii) Co-operation with the group. (iv) Tolerating opinions of others. 			

Grade 12 Third Term - Evaluation Plan - 3 (Combined Maths - II)

01. Competency : 2. Interprets the system of coplanar forces in the meaningful application of it in the day to day life.

Competency Level : 2.9 Investigates the effect of friction on equilibrium in terms of its sign.

02. Nature of Evaluation Plan : Is a group activity of investigating the equilibrium of a body on a rough surface.

03. Time : 90 minutes

04. Instructions for the implementation of the evaluation plan :

1. Three copies of work sheet in annexure 1
2. Triple beam balance, protractor, pulley, balance pan, strings and weights.
3. Some weights of low height.
4. Demi papers.
5. Marker pens, should be supplied.

- Step 1 :**
- (i) Divide the students into 3 groups A, B and C.
 - (ii) Provide each group with a copy of work sheet.
 - (iii) Get them engaged in the group activity.
 - (iv) Prepare them to present the explanations to the class.

05. Criteria for Evaluation :

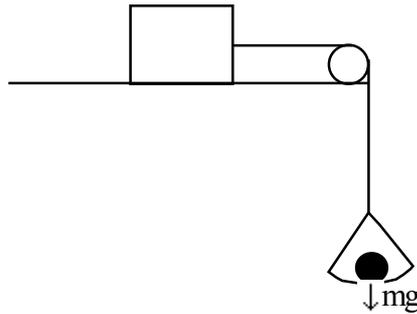
1. Expresses the conditions for the equilibrium of a body on a rough surface.
2. Realises that the frictional force is a quality endemic to the nature of the surfaces in contact.
3. Finds the conditions for the equilibrium of a body under frictional force.
4. Makes use of contradictions of an event suitably.
5. Applies suitable techniques to reach decisions.

Annexure 1

Work Sheet for Group 1

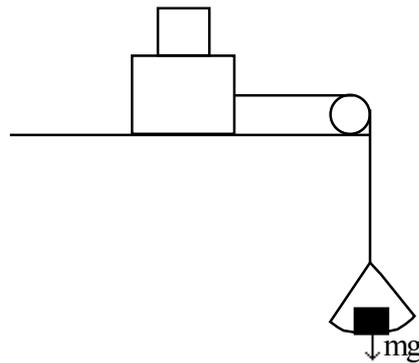
- Engage in the activity assigned to you.
- Be prepared to present group explanations.
- Discuss your observations within the group and reach reasonable conclusions.

Group A



- (i) Take several pieces of wood of different shapes and areas taken from the same board. Using an arrangement as shown above find the minimum force required to move each piece of wood on the table. Find $\frac{F_{lim}}{R}$ for each case.
- (ii) Repeat this for bodies made of surfaces with various materials and determine $\frac{F_{lim}}{R}$ for each. Analyse the results obtained in the two occasions.

Group B



Using an arrangement as shown above find the minimum force necessary to just move a piece of wood placed on a horizontal table. Repeating this for pieces of wood of increasing weights placed on it and determine the minimum force necessary to just move each. Draw a graph between the weight used to move and the total weight on the board with the board and analyse the results.

Group C

Place a small piece of wood on a plane and increase its inclination to the horizontal gradually. When the piece of wood is just about to move measure the inclination of the plane to the horizontal. Repeat this by placing decreasing weights on the piece of wood. Further measure the angles by replacing the piece of wood with bodies made of different materials. Analyse the results obtained.